### Verification

Lecture 6

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#### **REVIEW: Büchi automata**

A <u>nondeterministic Büchi automaton</u> (NBA) A is a tuple  $(Q, \Sigma, \delta, Q_0, F)$  where:

- *Q* is a finite set of states with  $Q_0 \subseteq Q$  a set of initial states
- Σ is an alphabet
- $\delta: Q \times \Sigma \to 2^Q$  is a transition function
- $F \subseteq Q$  is a set of accept (or: final) states

The size of  $\mathcal{A}$ , denoted  $|\mathcal{A}|$ , is the number of states and transitions in  $\mathcal{A}$ :

$$|\mathcal{A}| = |Q| + \sum_{q \in Q} \sum_{A \in \Sigma} |\delta(q, A)|$$

REVIEW: NBA and  $\omega$ -regular languages

The class of languages accepted by NBA

agrees with the class of  $\omega$ -regular languages

(1) any  $\omega$ -regular language is recognized by an NBA (2) for any NBA 4 the language  $C_{\rm eff}(4)$  is a regular

(2) for any NBA A, the language  $\mathcal{L}_{\omega}(A)$  is  $\omega$ -regular

REVIEW: For any  $\omega$ -regular language there is an NBA

• How to construct an NBA for the *w*-regular expression:

```
\mathbf{G} = \mathbf{E}_1 \cdot \mathbf{F}_1^{\omega} + \ldots + \mathbf{E}_n \cdot \mathbf{F}_n^{\omega} ?
```

where  $E_i$  and  $F_i$  are regular expressions over alphabet  $\Sigma$ ;  $\varepsilon \notin F_i$ 

- Rely on operations for NBA that mimic operations on ω-regular expressions:
  - (1) for NBA  $A_1$  and  $A_2$  there is an NBA accepting  $\mathcal{L}_{\omega}(A_1) \cup \mathcal{L}_{\omega}(A_2)$
  - (2) for any regular language  $\mathcal{L}$  with  $\varepsilon \notin \mathcal{L}$  there is an NBA accepting  $\mathcal{L}^{\omega}$
  - (3) for regular language L and NBA A' there is an NBA accepting L.L<sub>w</sub>(A')

#### REVIEW: NBA accept $\omega$ -regular languages

For each NBA  $\mathcal{A}$ :  $\mathcal{L}_{\omega}(\mathcal{A})$  is  $\omega$ -regular

#### **Proof:**

• Given an NBA  $\mathcal{A} = (Q, \Sigma, \delta, Q_0, F)$ , we define, for each pair  $s, s' \in Q$ , the regular language  $W_{s,s'}$ :

$$W_{s,s'} = \{u \in \Sigma^* \mid \mathsf{NFA}(Q, \Sigma, \delta, \{s\}, \{s'\}) \text{ accepts } u\}$$

$$\blacktriangleright \mathcal{L}_{\omega}(\mathcal{A}) = \bigcup_{s \in Q_0, s' \in F} W_{s,s'} \cdot W_{s',s'}^{\omega}$$

- Let  $E_{s,s'}$  be the regular expression defining the language  $W_{s,s'}$ .
- The corresponding ω-regular expression

$$\begin{split} & E_{s_1,s_1'}.E_{s_1',s_1'}^{\omega} + E_{s_2,s_1'}.E_{s_1',s_1'}^{\omega} + \dots \\ & \text{defines } \mathcal{L}_{\omega}(\mathcal{A}). \end{split}$$

### Checking non-emptiness

#### $\mathcal{L}_{\omega}(\mathcal{A}) \neq \emptyset$ if and only if

 $\exists q_0 \in Q_0. \exists q \in F. \exists w \in \Sigma^*. \exists v \in \Sigma^+. q \in \delta^*(q_0, w) \land q \in \delta^*(q, v)$ 

there is a reachable accept state on a cycle

The emptiness problem for NBA A can be solved in time  $\mathcal{O}(|A|)$ 

### Non-blocking NBA

- NBA  $\mathcal{A}$  is <u>non-blocking</u> if  $\delta(q, A) \neq \emptyset$  for all q and  $A \in \Sigma$ 
  - for each input word there exists an infinite run
- For each NBA A there exists a non-blocking NBA trap(A) with:
  - $|trap(\mathcal{A})| = \mathcal{O}(|\mathcal{A}|) \text{ and } \mathcal{A} \equiv trap(\mathcal{A})$
- For  $\mathcal{A} = (Q, \Sigma, \delta, Q_0, F)$  let  $trap(\mathcal{A}) = (Q', \Sigma, \delta', Q_0, F)$  with:

#### **Deterministic BA**

Büchi automaton  $\mathcal{A}$  is called <u>deterministic</u> if

$$|Q_0| \le 1$$
 and  $|\delta(q, A)| \le 1$  for all  $q \in Q$  and  $A \in \Sigma$   
DBA  $\mathcal{A}$  is called total if

 $|Q_0| = 1$  and  $|\delta(q, A)| = 1$  for all  $q \in Q$  and  $A \in \Sigma$ 

total DBA provide unique runs for each input word

### Example DBA for LT property



NBA are more expressive than DBA

#### NFA and DFA are equally expressive but NBA and DBA are not!

There is no DBA that accepts  $\mathcal{L}_{\omega}((A+B)^*B^{\omega})$ 

### Proof

- Assume that  $L = \mathcal{L}((A + B)^* B^\omega)$  is recognized by the deterministic Büchi automaton  $\mathcal{A}$ .
- Since  $b^{\omega} \in L$ , there is a run

```
r_0 = s_{0,0}s_{0,1}s_{0,2},...
with s_{0,n_0} \in F for some n_0 \in \mathbb{N}.
```

• Similarly,  $b^{n_0}ab^{\omega} \in L$  and there must be a run  $r_1 = s_{0,0}s_{0,1}s_{0,2}\dots s_{0,n_0}s_{1,0}s_{1,1}s_{1,2}\dots$ 

with  $s_{1,n_1} \in F$ 

- Repeating this argument, there is a word  $b^{n_0}ab^{n_1}ab^{n_2}a...$  accepted by A.
- This contradicts  $L = \mathcal{L}_{\omega}(\mathcal{A})$ .

#### The need for nondeterminism



let  $\{a\} = AP$ , i.e.,  $2^{AP} = \{A, B\}$  where  $A = \{\}$  and  $B = \{a\}$ "eventually forever a" equals  $(A + B)^* B^\omega = (\{\} + \{a\})^* \{a\}^\omega$ 

### Generalized Büchi automata

- NBA are as expressive as ω-regular languages
- Variants of NBA exist that are equally expressive
  - Muller, Rabin, and Streett automata
  - generalized Büchi automata (GNBA)
- GNBA are like NBA, but have a distinct acceptance criterion
  - ▶ a GNBA requires to visit several sets  $F_1, ..., F_k$  ( $k \ge 0$ ) infinitely often
  - ▶ for *k*=0, all runs are accepting
  - for k=1 this boils down to an NBA
- GNBA are useful to relate temporal logic and automata
  - but they are equally expressive as NBA

#### Generalized Büchi automata

A generalized NBA (GNBA)  $\mathcal{G}$  is a tuple  $(Q, \Sigma, \delta, Q_0, \mathcal{F})$  where:

- *Q* is a finite set of states with  $Q_0 \subseteq Q$  a set of initial states
- Σ is an alphabet
- $\delta: Q \times \Sigma \to 2^Q$  is a transition function
- $\mathcal{F} = \{F_1, \ldots, F_k\}$  is a (possibly empty) subset of  $2^Q$

The size of  $\mathcal{G}$ , denoted  $|\mathcal{G}|$ , is the number of states and transitions in  $\mathcal{G}$ :

$$|\mathcal{G}| = |Q| + \sum_{q \in Q} \sum_{A \in \Sigma} |\delta(q, A)|$$

#### Language of a GNBA

- GNBA  $\mathcal{G} = (Q, \Sigma, \delta, Q_0, \mathcal{F})$  and word  $\sigma = A_0 A_1 A_2 \ldots \in \Sigma^{\omega}$
- A *run* for  $\sigma$  in  $\mathcal{G}$  is an infinite sequence  $q_0 q_1 q_2 \dots$  such that: •  $a_0 \in O_0$  and  $a_i \xrightarrow{A_i} a_{i+1}$  for all 0 < i
- ▶ Run  $q_0 q_1 \dots$  is <u>accepting</u> if for all  $F \in \mathcal{F}$ :  $q_i \in F$  for infinitely many *i*
- $\sigma \in \Sigma^{\omega}$  is *accepted* by  $\mathcal{G}$  if there exists an accepting run for  $\sigma$
- ► The <u>accepted language</u> of G:
  - $\mathcal{L}_{\omega}(\mathcal{G}) = \{ \sigma \in \Sigma^{\omega} \mid \text{ there exists an accepting run for } \sigma \text{ in } \mathcal{G} \}$
- GNBA  $\mathcal{G}$  and  $\mathcal{G}'$  are <u>equivalent</u> if  $\mathcal{L}_{\omega}(\mathcal{G}) = \mathcal{L}_{\omega}(\mathcal{G}')$

### Example



# A GNBA for the property "both processes are infinitely often in their critical section"

#### From GNBA to NBA

#### For any GNBA $\mathcal{G}$ there exists an NBA $\mathcal{A}$ with:

$$\mathcal{L}_{\omega}(\mathcal{G}) = \mathcal{L}_{\omega}(\mathcal{A}) \text{ and } |\mathcal{A}| = \mathcal{O}(|\mathcal{G}| \cdot |\mathcal{F}|)$$

where  ${\mathcal F}$  denotes the set of acceptance sets in  ${\mathcal G}$ 

# Example



#### Product of Büchi automata

The product construction for finite automata does not work:



$$\mathcal{L}_{\omega}(\mathcal{A}_{1}) = \mathcal{L}_{\omega}(\mathcal{A}_{2}) = \{A^{\omega}\}, \text{ but } \mathcal{L}_{\omega}(\mathcal{A}_{1} \otimes \mathcal{A}_{2}) = \emptyset$$

# Product of Büchi automata



#### Intersection

# For GNBA $\mathcal{G}_1$ and $\mathcal{G}_2$ there exists a GNBA $\mathcal{G}$ with $\mathcal{L}_{\omega}(\mathcal{G}) = \mathcal{L}_{\omega}(\mathcal{G}_1) \cap \mathcal{L}_{\omega}(\mathcal{G}_2)$ and $|\mathcal{G}| = \mathcal{O}(|\mathcal{G}_1| + |\mathcal{G}_2|)$

### Facts about Büchi automata

- They are as expressive as ω-regular languages
- They are closed under various operations and also under  $\cap$ 
  - deterministic automaton -A accepts  $-\mathcal{L}_{\omega}(A)$
- Nondeterministic BA are more expressive than deterministic BA
- Emptiness check = check for reachable recurrent accept state
  - this can be done in  $\mathcal{O}(|\mathcal{A}|)$

### Verifying $\omega$ -regular properties

### **REVIEW:** Regular safety properties

Safety property  $P_{safe}$  over AP is <u>regular</u> if its set of bad prefixes is a regular language over  $2^{AP}$ 

### **REVIEW: Verifying regular safety properties**

Let *TS* over *AP* and NFA A with alphabet  $2^{AP}$  as before, regular safety property  $P_{safe}$  over *AP* such that  $\mathcal{L}(A)$  is the set of bad prefixes of  $P_{safe}$ 

The following statements are equivalent: (a)  $TS \models P_{safe}$ (b)  $Traces_{fin}(TS) \cap \mathcal{L}(\mathcal{A}) = \emptyset$ (c)  $TS \otimes \mathcal{A} \models P_{inv(\mathcal{A})}$ 

where 
$$P_{inv(A)}$$
 = "always"  $\neg F$ 

#### $\omega$ -regular properties

LT property *P* over *AP* is  $\underline{\omega}$ -regular if *P* is an  $\omega$ -regular language over 2<sup>*AP*</sup>

#### Basic idea of the algorithm

 $TS \notin P$  if and only if  $Traces(TS) \notin P$ 

if and only if  $Traces(TS) \cap (2^{AP})^{\omega} \setminus P \neq \emptyset$ 

if and only if  $Traces(TS) \cap \overline{P} \neq \emptyset$ 

if and only if  $Traces(TS) \cap \mathcal{L}_{\omega}(\mathcal{A}) \neq \emptyset$ 

if and only if  $TS \otimes A \models$  "eventually forever"  $\neg F$ 

persistence property

where A is an NBA accepting the complement property  $\overline{P} = (2^{AP})^{\omega} \setminus P$ 

#### Persistence property

A <u>persistence property</u> over *AP* is an LT property  $P_{pers} \subseteq (2^{AP})^{\omega}$ "eventually forever  $\Phi$ " for some propositional logic formula  $\Phi$  over *AP*:

$$P_{pers} = \left\{ A_0 A_1 A_2 \dots \in \left(2^{AP}\right)^{\omega} \mid \exists i \ge 0, \forall j \ge i, A_j \models \Phi \right\}$$

 $\Phi$  is called a persistence (or state) condition of  $P_{pers}$ 

" $\Phi$  is an invariant after a while"

### Example persistence property



let  $\{a\} = AP$ , i.e.,  $2^{AP} = \{A, B\}$  where  $A = \{\}$  and  $B = \{a\}$ "eventually forever a" equals  $(A + B)^* B^\omega = (\{\} + \{a\})^* \{a\}^\omega$ 

#### Synchronous product

For transition system  $TS = (S, Act, \rightarrow, I, AP, L)$  without terminal states and  $\mathcal{A} = (Q, \Sigma, \delta, Q_0, F)$  a non-blocking NBA with  $\Sigma = 2^{AP}$ , let:

$$TS \otimes \mathcal{A} = (S', Act, \rightarrow', I', AP', L')$$
 where

► 
$$S' = S \times Q$$
,  $AP' = Q$  and  $L'(\langle s, q \rangle) = \{q\}$ 

→' is the smallest relation defined by: s → t ∧ q → t ∧ q → p / (s,q) → (t,p)

I' = { (s<sub>0</sub>, q) | s<sub>0</sub> ∈ I ∧ ∃q<sub>0</sub> ∈ Q<sub>0</sub>, q<sub>0</sub> → (t,p) / (t,p) }

# Verifying $\omega$ -regular properties

Let:

- TS be a transition system over AP
- *P* be an  $\omega$ -regular property over *AP*, and
- $\mathcal{A}$  a non-blocking NBA such that  $\mathcal{L}_{\omega}(\mathcal{A}) = \overline{P}$ .

The following statements are equivalent: (a)  $TS \models P$ (b)  $Traces(TS) \cap \mathcal{L}_{\omega}(\mathcal{A}) = \emptyset$ (c)  $TS \otimes \mathcal{A} \models P_{pers(\mathcal{A})}$ 

where 
$$P_{pers(A)}$$
 = "eventually forever  $\neg F$ "

 $\Rightarrow$  checking  $\omega$ -regular properties is reduced to persistence checking!

# Infinitely often green?





### Infinitely often green?





### Persistence checking

- Aim: establish whether  $TS \notin P_{pers} =$  "eventually forever  $\Phi$ "
- Let state *s* be reachable in *TS* and  $s \neq \Phi$ 
  - TS has an initial path fragment that ends in s
- If s is on a cycle
  - this path fragment can be continued by an infinite path
  - ..... by traversing the cycle containing s infinitely often
- ⇒ *TS* may visit the  $\neg \Phi$ -state *s* infinitely often and so: *TS*  $\neq$  *P*<sub>pers</sub>
  - If no such s is found then:  $TS \models P_{pers}$

# Cycle detection

How to check for a reachable cycles containing a  $\neg \Phi$ -state?

- Alternative 1:
  - compute the strongly connected components (SCCs) in G(TS)
  - check whether one such SCC is reachable from an initial state
  - ► . . . that contains a ¬Φ-state
  - "eventually forever  $\Phi$ " is refuted if and only if such SCC is found
- Alternative 2:
  - use a nested depth-first search
  - ⇒ more adequate for an on-the-fly verification algorithm
  - $\Rightarrow$  easier for generating counterexamples

let's have a closer look into this by first dealing with two-phase DFS

### A two-phase depth first-search

1. Determine all  $\neg \Phi$ -states that are reachable from some initial state

this is performed by a standard depth-first search

- 2. For each reachable  $\neg \Phi$ -state, check whether it belongs to a cycle
  - start a depth-first search in s
  - check for all states reachable from s whether there is an "backward" edge to s
  - Time complexity:  $\Theta(N \cdot |\Phi| \cdot (N+M))$ 
    - where N is the number of states and M the number of transitions
    - fragments reachable via  $K \neg \Phi$ -states are searched K times

### Two-phase depth first-search

**Require:** finite transition system *TS* without terminal states, and proposition  $\Phi$ 

**Ensure:** "yes" if  $TS \models$  "eventually forever  $\Phi$ ", otherwise "no".

**set of** states  $R := \emptyset$ ;  $R_{\neg \Phi} := \emptyset$ ; {set of reachable states resp.  $\neg \Phi$ -states} **stack of** states  $U := \varepsilon$ ; {DFS-stack for first DFS, initial empty} **set of** states  $T := \emptyset$ ; {set of visited states for the cycle check} **stack of** states  $V := \varepsilon$ ; {DFS-stack for the cycle check}

for all  $s \in I \setminus R$  do visit(s); od {phase one} for all  $s \in R_{\neg \Phi}$  do

 $T := \emptyset; V := \varepsilon; \{\text{phase two}\}$ 

if cycle\_check(s) then return "no" {s belongs to a cycle}
end for

return "yes" {none of the  $\neg \Phi$ -states belongs to a cycle}

#### Find $\neg \Phi$ -states

process visit (state s) push(s, U); {push s on the stack}  $R := R \cup \{s\}; \{\text{mark } s \text{ as reachable}\}$ repeat s' := top(U);if  $Post(s') \subseteq R$  then pop(U);if  $s' \not\models \Phi$  then  $R_{\neg \Phi} := R_{\neg \Phi} \cup \{s'\}$ ; fi else let  $s'' \in Post(s') \setminus R$ push(s'', U); $R := R \cup \{s''\}$ ; {state s'' is a new reachable state} end if until  $(U = \varepsilon)$  endproc

# Cycle detection

```
process boolean cycle_check(state s)
 boolean cycle_found := false; {no cycle found yet}
push(s, V); T := T \cup \{s\}; \{push s on the stack\}
 repeat
    s' := top(V); {take top element of V}
    if s \in Post(s') then
       cycle_found := true; {if s \in Post(s'), a cycle is found }
       push(s, V); {push s on the stack}
    else
       if Post(s') \setminus T \neq \emptyset then
           let s'' \in Post(s') \setminus T;
           push(s'', V); T := T \cup \{ s'' \}; \{ push an unvisited successor of s' \}
           else pop(V); {unsuccessful cycle search for s'}
       end if
    end if
 until ((V = \varepsilon) \lor cycle found)
 return cycle_found endproc
```

### Nested depth-first search

- Idea: perform the two depth-first searches in an <u>interleaved</u> way
  - the outer DFS serves to encounter all reachable  $\neg \Phi$ -states
  - the inner DFS seeks for backward edges leading to the  $\neg\Phi\text{-state}$
- Nested DFS
  - on full expansion of  $\neg \Phi$ -state s in the outer DFS, start inner DFS
  - in inner DFS, visit all states reachable from s not visited in the inner DFS yet
  - no backward edge found to s? continue the outer DFS (look for next ¬Φ state)
- Counterexample generation: DFS stack concatenation
  - ► stack *U* for the outer DFS = path fragment from  $s_0 \in I$  to *s* (in reversed order)
  - stack V for the inner DFS = a cycle from state s to s (in reversed order)

# The outer DFS (1)

**Require:** transition system TS without terminal states, and proposition  $\Phi$ **Ensure:** "yes" if  $TS \models$  "eventually forever  $\Phi$ ", otherwise "no" plus counterexample

```
set of states R := \emptyset; {set of visited states in the outer DFS}
stack of states U := \varepsilon; {stack for the outer DFS}
set of states T := \emptyset; {set of visited states in the inner DFS}
stack of states V := \varepsilon; {stack for the inner DFS}
boolean cycle_found := false;
```

```
while (I \setminus R \neq \emptyset \land \neg cycle\_found) do
   let s \in I \setminus R; {explore the reachable}
    reachable_cycle(s); {fragment with outer DFS}
```

#### end while

```
if ¬cycle_found then
```

```
return ("yes") {TS \models "eventually forever \Phi"}
```

#### مادم

```
return ("no", reverse(V.U)) {stack contents yield a counterexample}
end if
```

### The outer DFS (2)

```
process reachable_cycle (state s)
push(s, U); {push s on the stack}
R \coloneqq R \cup \{s\};
repeat
   s' := top(U);
   if Post(s') \setminus R \neq \emptyset then
       let s'' \in Post(s') \setminus R;
       push(s'', U); {push the unvisited successor of s'}
       R := R \cup \{ s'' \}; \{ and mark it reachable \}
   else
       pop(U); {outer DFS finished for s'}
       if s' \neq \Phi then
          cycle_found := cycle_check(s'); {proceed with the inner}
          {DFS in state s'}
       end if
   end if
until ((U = \varepsilon) \lor cycle_found) {stop when stack for the outer}
```

```
{DFS is empty or cycle found} endproc
```

### Correctness of nested DFS

Let:

- > TS be a finite transition system over AP without terminal states and
- *P*<sub>pers</sub> a persistence property

The nested DFS algorithm yields "no" if and only if  $TS \notin P_{pers}$ 

### Time complexity

# The worst-case time complexity of nested DFS is in $O((N+M) + N \cdot |\Phi|)$

where *N* is # reachable states in *TS*, and *M* is # transitions in *TS* 

### Linear-time Temporal Logic

### Syntax

modal logic over infinite sequences [Pnueli 1977]

- Propositional logic
  - ▶ a ∈ AP
  - $\neg \phi$  and  $\phi \land \psi$
- Temporal operators
  - $\bigcirc \phi$
  - ► φUψ

atomic proposition negation and conjunction

next state fulfills  $\phi$  $\phi$  holds Until a  $\psi$ -state is reached

linear temporal logic is a logic for describing LT properties

#### **Derived operators**

$$\phi \lor \psi \equiv \neg (\neg \phi \land \neg \psi)$$
  

$$\phi \Rightarrow \psi \equiv \neg \phi \lor \psi$$
  

$$\phi \Leftrightarrow \psi \equiv (\phi \Rightarrow \psi) \land (\psi \Rightarrow \phi)$$
  

$$\phi \oplus \psi \equiv (\phi \land \neg \psi) \lor (\neg \phi \land \psi)$$
  
true 
$$\equiv \phi \lor \neg \phi$$
  
false 
$$\equiv \neg \text{true}$$
  

$$\diamond \phi \equiv \text{true U} \phi \quad \text{"sometimes in the future"}$$
  

$$\Box \phi \equiv \neg \diamond \neg \phi \quad \text{"from now on forever"}$$

precedence order: the unary operators bind stronger than the binary ones.  $\neg$  and  $\bigcirc$  bind equally strong. U takes precedence over  $\land$ ,  $\lor$ , and  $\rightarrow$ 

#### Intuitive semantics



# Traffic light properties

• Once red, the light cannot become green immediately:

$$\Box(red \Rightarrow \neg \bigcirc green)$$

- ► The light becomes green eventually: <> green
- Once red, the light always becomes green eventually:  $\Box$  (red  $\Rightarrow \Diamond$  green)
- Once red, the light always becomes green eventually after being yellow for some time inbetween:

 $\Box(\textit{red} \rightarrow \bigcirc (\textit{red} \, U\,(\textit{yellow} \land \bigcirc (\textit{yellow} \, U\,\textit{green}))))$ 

#### Semantics over words

The LT-property induced by LTL formula  $\varphi$  over AP is:

 $Words(\varphi) = \left\{ \sigma \in \left(2^{AP}\right)^{\omega} \mid \sigma \models \varphi \right\}$ , where  $\models$  is the smallest relation satisfying:

 $\sigma \models \text{ true}$   $\sigma \models a \quad \text{iff} \quad a \in A_0 \quad (\text{i.e., } A_0 \models a)$   $\sigma \models \varphi_1 \land \varphi_2 \quad \text{iff} \quad \sigma \models \varphi_1 \text{ and } \sigma \models \varphi_2$   $\sigma \models \neg \varphi \quad \text{iff} \quad \sigma \notin \varphi$   $\sigma \models \bigcirc \varphi \quad \text{iff} \quad \sigma [1..] = A_1 A_2 A_3 \ldots \models \varphi$   $\sigma \models \varphi_1 \cup \varphi_2 \quad \text{iff} \quad \exists j \ge 0. \ \sigma[j..] \models \varphi_2 \text{ and } \sigma[i..] \models \varphi_1, \ 0 \le i < j$ 

for  $\sigma = A_0A_1A_2...$  we have  $\sigma[i..] = A_iA_{i+1}A_{i+2}...$  is the suffix of  $\sigma$  from index *i* on

### Semantics over paths and states

Let  $TS = (S, Act, \rightarrow, I, AP, L)$  be a transition system without terminal states, and let  $\varphi$  be an LTL-formula over *AP*.

• For infinite path fragment  $\pi$  of *TS*:

$$\pi \vDash \varphi$$
 iff  $trace(\pi) \vDash \varphi$ 

• For state  $s \in S$ :

 $s \vDash \varphi$  iff  $(\forall \pi \in Paths(s), \pi \vDash \varphi)$ 

► *TS* satisfies  $\varphi$ , denoted *TS*  $\models \varphi$ , if *Traces*(*TS*)  $\subseteq$  *Words*( $\varphi$ )

#### Semantics for transition systems

 $TS \vDash \varphi$ 

iff (\* transition system semantics \*)  $Traces(TS) \subseteq Words(\varphi)$ iff (\* definition of  $\vDash$  for LT-properties \*)  $TS \vDash Words(\varphi)$ iff (\* Definition of  $Words(\varphi)$  \*)  $\pi \vDash \varphi$  for all  $\pi \in Paths(TS)$ 

iff (\* semantics of  $\models$  for states \*)

 $s_0 \models \varphi$  for all  $s_0 \in I$ .

# Example



#### Semantics of negation

For paths, it holds  $\pi \vDash \varphi$  if and only if  $\pi \not\models \neg \varphi$  since:

$$Words(\neg \varphi) = (2^{AP})^{\omega} \setminus Words(\varphi)$$

But:  $TS \neq \varphi$  and  $TS \models \neg \varphi$  are <u>not</u> equivalent in general It holds:  $TS \models \neg \varphi$  implies  $TS \neq \varphi$ . Not always the reverse! Note that:

$$TS \neq \varphi \quad \text{iff } Traces(TS) \notin Words(\varphi)$$
$$\text{iff } Traces(TS) \smallsetminus Words(\varphi) \neq \emptyset$$
$$\text{iff } Traces(TS) \cap Words(\neg \varphi) \neq \emptyset$$

*TS* neither satisfies  $\varphi$  nor  $\neg \varphi$  if there are paths  $\pi_1$  and  $\pi_2$  in *TS* such that  $\pi_1 \vDash \varphi$  and  $\pi_2 \vDash \neg \varphi$ 

### Example



#### A transition system for which $TS \neq \Diamond a$ and $TS \neq \neg \Diamond a$