

# Verification

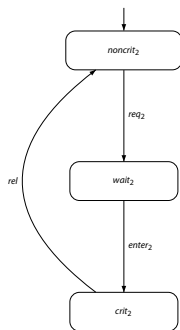
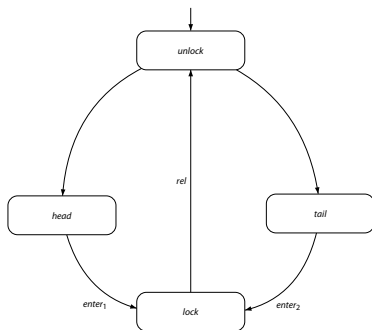
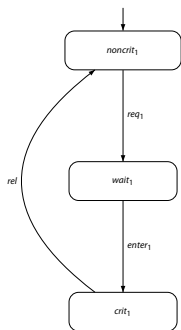
## Lecture 11

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# Randomized arbiter



$TS_1 \parallel \text{Arbiter} \parallel TS_2 \not\models \text{AG AF } \textit{crit}_1$   
But:  $TS_1 \parallel \text{Arbiter} \parallel TS_2 \models_{\textit{fair}} \text{AG AF } \textit{crit}_1 \wedge \text{AG AF } \textit{crit}_2$  with  
 $\textit{fair} = \text{GF } \textit{head} \wedge \text{GF } \textit{tail}$

## REVIEW: CTL fairness constraints

- ▶ A strong CTL fairness constraint is a formula of the form:

$$sfair = \bigwedge_{0 < i \leq k} (GF \Phi_i \rightarrow GF \Psi_i)$$

where  $\Phi_i$  and  $\Psi_i$  (for  $0 < i \leq k$ ) are CTL-formulas over  $AP$ .

- ▶ A weak CTL fairness constraint is a formula of the form:

$$wfair = \bigwedge_{0 < i \leq k} (FG \Phi_i \rightarrow GF \Psi_i)$$

- ▶ a CTL fairness assumption *fair* is a conjunction of CTL fairness constraints.
- ⇒ a CTL fairness constraint is an LTL formula over CTL state formulas!

# REVIEW: Semantics of fair CTL

For CTL fairness assumption *fair*, relation  $\models_{fair}$  is defined by:

$s \models_{fair} a$	iff $a \in Label(s)$
$s \models_{fair} \neg \Phi$	iff $\neg (s \models_{fair} \Phi)$
$s \models_{fair} \Phi \vee \Psi$	iff $(s \models_{fair} \Phi) \vee (s \models_{fair} \Psi)$
$s \models_{fair} E \varphi$	iff $\pi \models_{fair} \varphi$ for <u>some fair</u> path $\pi$ that starts in $s$
$s \models_{fair} A \varphi$	iff $\pi \models_{fair} \varphi$ for <u>all fair</u> paths $\pi$ that start in $s$

$\pi \models_{fair} X \Phi$	iff $\pi[1] \models_{fair} \Phi$
$\pi \models_{fair} \Phi U \Psi$	iff $(\exists j \geq 0. \pi[j] \models_{fair} \Psi \wedge (\forall 0 \leq k < j. \pi[k] \models_{fair} \Phi))$

$\pi$  is a fair path iff  $\pi \models_{fair}$  for CTL fairness assumption *fair*

## REVIEW: Fair CTL model checking

- ▶ Determine  $Sat_{fair}(EG \text{ true}) = \{q \in S \mid FairPaths(q) \neq \emptyset\}$
- ▶ Introduce an atomic proposition  $a_{fair}$  such that:
  - ▶  $a_{fair} \in L(q)$  if  $q \in Sat_{fair}(EG \text{ true})$
- ▶ Compute the sets  $Sat_{fair}(\Psi)$  for all subformulas  $\Psi$  of  $\Phi$  (in ENF)

$$Sat_{fair}(a) = \{q \in S \mid a \in L(q)\}$$

$$Sat_{fair}(\neg a) = S \setminus Sat_{fair}(a)$$

by:  $Sat_{fair}(a \wedge a') = Sat_{fair}(a) \cap Sat_{fair}(a')$

$$Sat_{fair}(EX a) = Sat(EX(a \wedge a_{fair}))$$

$$Sat_{fair}(E(a U a')) = Sat(E(a U (a' \wedge a_{fair})))$$

$$Sat_{fair}(EG a) = (\text{to be discussed})$$

- ▶ Thus: model checking CTL under fairness constraints is
  - ▶ CTL model checking + algorithm for computing  $Sat_{fair}(EG a)$ !

## Characterization of $Sat_{fair}(EG a)$

$$q \models_{sfair} EG a \quad \text{where} \quad sfair = \bigwedge_{0 < i \leq k} (GF b_i \rightarrow GF c_i)$$

iff there exists a finite path fragment  $q_0 \dots q_n$  and a cycle  $q'_0 \dots q'_r$  with:

1.  $q_0 = q$  and  $q_n = q'_0 = q'_r$
2.  $q_i \models a$ , for all  $0 \leq i \leq n$ , and  $q'_j \models a$ , for all  $0 \leq j \leq r$ , and
3.  $Sat(b_i) \cap \{q'_1, \dots, q'_r\} = \emptyset$  or  
 $Sat(c_i) \cap \{q'_1, \dots, q'_r\} \neq \emptyset$  for  $0 < i \leq k$

## Computing $Sat_{fair}(EG a)$

- ▶ Consider state  $q$  only if  $q \models a$ , otherwise eliminate  $q$ 
  - ▶ change  $TS$  into  $TS[a] = (S', Act, \rightarrow', I', AP, L')$  with  $S' = Sat(a)$ ,
  - ▶  $\rightarrow' = \rightarrow \cap (S' \times Act \times S')$ ,  $I' = I \cap S'$ , and  $L'(s) = L(s)$  for  $s \in S'$
  - ⇒ each infinite path fragment in  $TS[a]$  satisfies  $G a$
- ▶  $q \models_{fair} EG a$  iff there is a non-trivial SCC  $D$  in  $TS[a]$  reachable from  $q$  such that
  - ▶  $D \cap Sat(b_i) = \emptyset$     or
  - ▶  $D \cap Sat(c_i) \neq \emptyset$for  $0 < i \leq k$
- ▶  $Sat_{sfair}(EG a) = \{q \in S \mid Reach_{TS[a]}(s) \cap T \neq \emptyset\}$ 
  - ▶  $T$  is the union of all such SCCs  $D$ .

how to compute  $T$ ?

## Unconditional fairness

$$ufair \equiv \bigwedge_{0 < i \leq k} GF b_i$$

Let  $T$  be the set union of all non-trivial SCCs  $C$  of  $TS[a]$  satisfying

$$C \cap Sat(b_i) \neq \emptyset \quad \text{for all } 0 < i \leq k$$

It now follows:

$$s \models_{ufair} EG a \quad \text{if and only if} \quad Reach_{G[a]}(s) \cap T \neq \emptyset$$

$\Rightarrow T$  can be determined by a simple graph analysis (DFS)



## Strong fairness: single constraint ( $k = 1$ )

- ▶  $sfair = GF b_1 \rightarrow GF c_1$
- ▶  $q \models_{sfair} EG a$  iff  $C$  is a non-trivial SCC in  $TS[a]$  reachable from  $q$  with:
  - (1)  $C \cap Sat(c_1) \neq \emptyset$ , or
  - (2) there exists a non-trivial SCC  $D$  in  $C[-b_1]$
- ▶ For the union  $T$  of all such SCCs  $C$ :

$q \models_{sfair} EG a$  if and only if  $Reach_{S[a]}(q) \cap T \neq \emptyset$

## Strong fairness: general case ( $k > 1$ )

Check each non-trivial SCC  $C$  recursively as follows:

Check( $C, \bigwedge_{0 < i \leq k} (GF b_i \rightarrow GF c_i)$ ):

**if**  $\forall i \in \{1, \dots, k\} : C \cap Sat(c_i) \neq \emptyset$  **return true**

**else**

**choose** some  $j \in \{1, \dots, k\} : C \cap Sat(c_j) = \emptyset$ .

remove all states in  $Sat(b_j)$  from  $C$

**for all** non-trivial SCCs  $D$  do

**if** Check( $D, \bigwedge_{0 < i \leq k, i \neq j} (GF b_i \rightarrow GF c_i)$ ) **return true**

**return false**

$T$  is the union of all SCCs  $C$  that pass the check.

## Time complexity

For state graph  $TS$  with  $N$  states and  $M$  edges,  
CTL formula  $\Phi$ , and CTL fairness constraint *fair* with  $k$  conjuncts,  
the CTL model-checking problem  $TS \models_{\text{fair}} \Phi$   
can be determined in time  $\mathcal{O}(|\Phi| \cdot (N + M) \cdot k)$

## Syntax of CTL\*

CTL\* state-formulas are formed according to:

$$\Phi ::= \text{true} \mid a \mid \Phi_1 \wedge \Phi_2 \mid \neg\Phi \mid E\varphi$$

where  $a \in AP$  and  $\varphi$  is a path-formula

CTL\* path-formulas are formed according to the grammar:

$$\varphi ::= \Phi \mid \varphi_1 \wedge \varphi_2 \mid \neg\varphi \mid X\varphi \mid \varphi_1 U \varphi_2$$

where  $\Phi$  is a state-formula, and  $\varphi, \varphi_1$  and  $\varphi_2$  are path-formulas

$$\text{in CTL*}: A\varphi = \neg E\neg\varphi.$$

# CTL\* semantics

$s \models a$	iff	$a \in L(s)$
$s \models \neg \Phi$	iff	not $s \models \Phi$
$s \models \Phi \wedge \Psi$	iff	$(s \models \Phi)$ and $(s \models \Psi)$
$s \models E \varphi$	iff	$\pi \models \varphi$ for some $\pi \in Paths(s)$

$\pi \models \Phi$	iff	$\pi[0] \models \Phi$
$\pi \models \varphi_1 \wedge \varphi_2$	iff	$\pi \models \varphi_1$ and $\pi \models \varphi_2$
$\pi \models \neg \varphi$	iff	not $\pi \models \varphi$
$\pi \models X \Phi$	iff	$\pi[1..] \models \Phi$
$\pi \models \Phi U \Psi$	iff	$\exists j \geq 0. (\pi[j..] \models \Psi \wedge (\forall 0 \leq k < j. \pi[k..] \models \Phi))$

## State graph semantics

- ▶ For CTL\*-state-formula  $\Phi$ , the satisfaction set  $Sat(\Phi)$  is defined by:

$$Sat(\Phi) = \{q \in S \mid q \models \Phi\}$$

- ▶  $TS$  satisfies CTL\*-formula  $\Phi$  iff  $\Phi$  holds in all its initial states:

$$TS \models \Phi \quad \text{if and only if} \quad \forall q \in I. q_0 \models \Phi$$

this is exactly as for CTL

# Embedding of LTL in CTL\*

For LTL formula  $\varphi$  and  $TS$  without terminal states (both over  $AP$ ) and for each  $q \in S$ :

$$\underbrace{q \models \varphi}_{\text{LTL semantics}} \quad \text{if and only if} \quad \underbrace{q \models A\varphi}_{\text{CTL}^* \text{ semantics}}$$

In particular:

$$TS \models_{\text{LTL}} \varphi \quad \text{if and only if} \quad TS \models_{\text{CTL}^*} A\varphi$$

## CTL\* is more expressive than LTL and CTL

For the CTL\*-formula over  $AP = \{a, b\}$ :

$$\Phi = (AFG a) \vee (AGEF b)$$

there does not exist any equivalent LTL- or CTL formula



## This logic is as expressive as CTL

CTL<sup>+</sup> state-formulas are formed according to:

$$\Phi ::= \text{true} \mid a \mid \Phi_1 \wedge \Phi_2 \mid \neg\Phi \mid E\varphi \mid A\varphi$$

where  $a \in AP$  and  $\varphi$  is a path-formula

CTL<sup>+</sup> path-formulas are formed according to the grammar:

$$\varphi ::= \varphi_1 \wedge \varphi_2 \mid \neg\varphi \mid X\Phi \mid \Phi_1 U \Phi_2$$

where  $\Phi, \Phi_1, \Phi_2$  are state-formulas, and  $\varphi, \varphi_1$  and  $\varphi_2$  are path-formulas

## CTL<sup>+</sup> is as expressive as CTL

For example:

$$\underbrace{E(Fa \wedge Fb)}_{\text{CTL}^+ \text{ formula}} \equiv \underbrace{EF(a \wedge EFb) \vee EF(b \wedge EFa)}_{\text{CTL formula}}$$

Some rules for transforming CTL<sup>+</sup> formulas into equivalent CTL ones:

$$E(\neg(\Phi_1 \cup \Phi_2)) \equiv E((\Phi_1 \wedge \neg\Phi_2) \cup (\neg\Phi_1 \wedge \neg\Phi_2)) \vee EG\neg\Phi_2$$

$$E(X\Phi_1 \wedge X\Phi_2) \equiv EX(\Phi_1 \wedge \Phi_2)$$

$$E(X\Phi \wedge (\Phi_1 \cup \Phi_2)) \equiv (\Phi_2 \wedge EX\Phi) \vee (\Phi_1 \wedge EX(\Phi \wedge E(\Phi_1 \cup \Phi_2)))$$

$$E((\Phi_1 \cup \Phi_2) \wedge (\Psi_1 \cup \Psi_2)) \equiv E((\Phi_1 \wedge \Psi_1) \cup (\Phi_2 \wedge E(\Psi_1 \cup \Psi_2))) \vee$$

$$E((\Phi_1 \wedge \Psi_1) \cup (\Psi_2 \wedge E(\Phi_1 \cup \Phi_2)))$$

⋮

adding boolean combinations of path formulas to CTL does not change its  
expressiveness

but CTL<sup>+</sup> formulas can be much shorter than shortest equivalent CTL formulas

# CTL\* model checking

- ▶ Adopt the same bottom-up procedure as for (fair) CTL
- ▶ Replace each maximal proper state subformula  $\Psi$  by new proposition  $a_\Psi$ 
  - ▶  $a_\Psi \in L(s)$  if and only if  $s \in Sat(\Psi)$
- ▶ Most interesting case: formulas of the form  $E \varphi$ 
  - ▶ by replacing all maximal state sub-formulas in  $\varphi$ , an LTL-formula results!
- ▶  $q \models E \varphi$  iff  $\underbrace{q \not\models A \neg \varphi}_{\text{CTL* semantics}}$  iff  $\underbrace{q \not\models \neg \varphi}_{\text{LTL semantics}}$ 
  - ▶  $Sat_{CTL^*}(E \varphi) = S \setminus Sat_{LTL}(\neg \varphi)$

# CTL\* model-checking algorithm

**for all**  $i \leq |\Phi|$  **do**

**for all**  $\Psi \in \text{Sub}(\Phi)$  with  $|\Psi| = i$  **do**

**switch**( $\Psi$ ):

true :  $\text{Sat}(\Psi) := S$ ;

$a$  :  $\text{Sat}(\Psi) := \{q \in S \mid a \in L(q)\}$ ;

$a_1 \wedge a_2$  :  $\text{Sat}(\Psi) := \text{Sat}(a_1) \cap \text{Sat}(a_2)$ ;

$\neg a$  :  $\text{Sat}(\Psi) := S \setminus \text{Sat}(a)$ ;

$E\varphi$  : **determine  $\text{Sat}_{LTL}(\neg\varphi)$  by means of an LTL model checker;**

:  **$\text{Sat}(\Psi) := S \setminus \text{Sat}_{LTL}(\neg\varphi)$**

**end switch**

$AP := AP \cup \{a_\Psi\}$ ; {introduce fresh atomic proposition}

replace  $\Psi$  with  $a_\Psi$

**forall**  $q \in \text{Sat}(\Psi)$  **do**  $L(q) := L(q) \cup \{a_\Psi\}$ ; **od**

**end for**

**end for**

**return**  $I \subseteq \text{Sat}(\Phi)$

## Time complexity

For transition system  $TS$  with  $N$  states and  $M$  transitions, CTL\* formula  $\Phi$ , the CTL\* model-checking problem  $TS \models \Phi$  can be determined in time  $\mathcal{O}((N+M) \cdot 2^{|\Phi|})$ .

the CTL\* model-checking problem is PSPACE-complete

# Counterexamples

- ▶ Model checking is an effective and efficient “bug hunting” technique
- ▶ Counterexamples are of utmost importance:
  - ▶ diagnostic feedback, the key to abstraction-refinement, schedule synthesis . . .
- ▶ LTL: counterexamples are finite paths
  - ▶  $X \Phi$ : a path on which the next state refutes  $\Phi$
  - ▶  $G \Phi$ : a path leading to a  $\neg \Phi$ -state
  - ▶  $F \Phi$ : a  $\neg \Phi$ -path leading to a  $\neg \Phi$  cycle
- ▶ Counterexample generation for LTL:
  - ▶ use stack contents of nested DFS on encountering an accept cycle
  - ▶ use a variant of BFS to find shortest counterexamples

# Counterexamples in CTL

- ▶  $TS \not\models A \varphi$  where  $\varphi$  only contains universal path quantifiers
  - ▶ **counterexample** = a sufficiently long prefix of a path refuting  $\varphi$  (as in LTL)
  - ▶ this fragment of the logic is known as universal fragment of CTL
- ▶  $TS \not\models E \varphi$  where  $\varphi$  is arbitrary CTL formula
  - ▶ all paths satisfy  $\neg\varphi!$   $\Rightarrow$  no clear notion of counterexample
  - ▶ **witness** = a sufficiently long prefix of a path satisfying  $\varphi$
- ▶ So:
  - ▶ for  $A \varphi$ , a prefix of  $\pi$  with  $\pi \not\models \varphi$  acts as **counterexample**
  - ▶ for  $E \varphi$ , a prefix of  $\pi$  with  $\pi \models \varphi$  acts as **witness**

## Counterexamples for $X \Phi$

- ▶ A counterexample of  $X \Phi$  is a path fragment  $q q'$  with
  - ▶  $q \in I$  and  $q' \in Post(q)$  with  $q' \not\models \Phi$
- ▶ A witness of  $X \Phi$  is a path fragment  $q q'$  with
  - ▶  $q \in I$  and  $q' \in Post(q)$  with  $q' \models \Phi$
- ▶ **Algorithm:** inspection of direct successors of initial states



## Counterexamples for $G \models \Phi$

- ▶ Counterexample is initial path fragment  $q_0 q_1 \dots q_n$  such that:
  - ▶  $q_0, \dots, q_{n-1} \models \Phi$  and  $q_n \not\models \Phi$
- ▶ Algorithm: backward search starting in  $\neg\Phi$ -states
- ▶ A witness of  $\varphi = G \models \Phi$  consists of an initial path fragment of the form:
  - ▶  $\underbrace{q_0 q_1 \dots q_n q'_1 \dots q'_r}_{\text{satisfy } \Phi}$  with  $q_n = q'_r$
- ▶ Algorithm: cycle search in the digraph  $G = (S, E')$  where the set of edges  $E'$ :
  - ▶  $E' = \{ (q, q') \mid q' \in \text{Post}(q) \wedge q \models \Phi \}$

## Counterexamples for $\Phi \cup \Psi$

- ▶ A witness is an initial path fragment  $q_0 q_1 \dots q_n$  with
  - ▶  $q_n \models \Psi$  and  $q_i \models \Phi$  for  $0 \leq i < n$
- ▶ **Algorithm:** backward search starting in the set of  $\Psi$ -states
- ▶ A counterexample is an initial path fragment that indicates a path  $\pi$ :
  - ▶ for which either
$$\pi \models G(\Phi \wedge \neg\Psi) \quad \text{or} \quad \pi \models (\Phi \wedge \neg\Psi) \cup (\neg\Phi \wedge \neg\Psi)$$
- ▶ Counterexample is initial path fragment of either form:
  - ▶  $q_0 \dots q_{n-1} \underbrace{q_n q'_1 \dots q'_r}_{\text{cycle}} \quad \text{with } q_n = q'_r$   
 $\underbrace{\hspace{10em}}_{\text{satisfy } \Phi \wedge \neg\Psi}$
  - ▶  $\underbrace{q_0 \dots q_{n-1}}_{\text{satisfy } \Phi \wedge \neg\Psi} \quad q_n \quad \text{with } q_n \models \neg\Phi \wedge \neg\Psi$

## Counterexample generation

- ▶ Determine the SCCs of the digraph  $G = (S, E')$  where

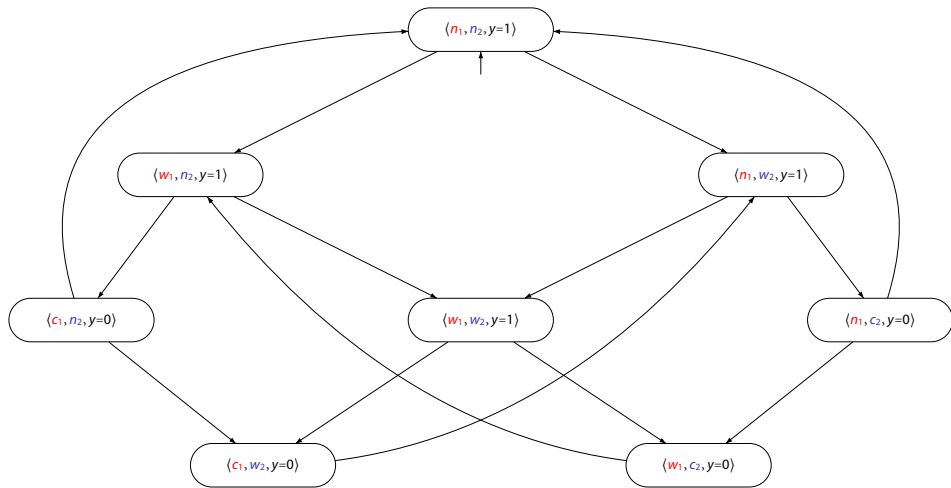
$$E' = \{ (q, q') \in S \times S \mid q' \in \text{Post}(q) \wedge q \models \Phi \wedge \neg\Psi \}$$

- ▶ Each path in  $G$  that starts in an initial state  $q_0 \in I$  and leads to a **non-trivial** SCC  $C$  in  $G$  provides a counterexample of the form:

$$q_0 q_1 \dots q_n \underbrace{q'_1 \dots q'_r}_{\in C} \quad \text{with} \quad q_n = q'_r$$

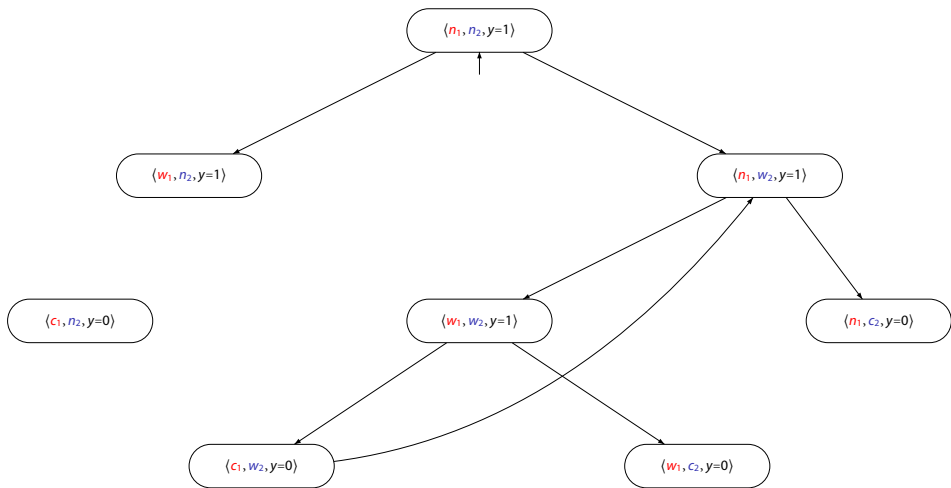
- ▶ Each path in  $G$  that leads from an initial state  $q_0$  to a **trivial** terminal SCC  $C = \{ q' \}$  with  $q' \not\models \Psi$  provides a counterexample of the form  $q_0 q_1 \dots q_n$  with  $q_n \models \neg\Phi \wedge \neg\Psi$

# Example



$$A \left( \underbrace{((n_1 \wedge n_2) \vee w_2)}_{\Phi} \cup \underbrace{c_2}_{\Psi} \right)$$

# SCC graph



## Time complexity

Let  $TS$  be a transition system  $TS$  with  $N$  states and  $K$  transitions and  $\varphi$  a CTL- path formula

If  $TS \not\models A \varphi$  then a counterexample for  $\varphi$  in  $TS$  can be determined in time  $\mathcal{O}(N+K)$ .

The same holds for a witness for  $\varphi$ , provided that  $TS \models E \varphi$ .

## Summary of CTL model checking (1)

- ▶ CTL is a logic for formalizing properties over computation **trees**
- ▶ The expressiveness of LTL and CTL is incomparable
- ▶ Fairness constraints cannot be expressed in CTL
  - ▶ but are incorporated by adapting the CTL semantics such that quantification is over fair paths
- ▶ CTL model checking is by a recursive descent over parse tree of  $\Phi$ 
  - ▶  $Sat(E(\Phi U \Psi))$  is determined using a least fixed point computation
  - ▶  $Sat(EG\Phi)$  is determined by a greatest fixed point computation

## Summary of CTL model checking (2)

- ▶ Time complexity of CTL model-checking  $TS \models \Phi$  is:
  - ▶ is linear in  $|TS|$  and  $|\Phi|$  and linear in  $k$  for  $k$  fairness constraints
- ▶ Checking  $TS \models_{fair} \Phi$  is  $TS \models \Phi$  plus computing  $Sat_{fair}(EG a)$
- ▶ Counterexamples and witnesses for CTL path-formulas can be determined using graph algorithms
- ▶ CTL\* is more expressive than both CTL and LTL
- ▶ The CTL\* model-checking problem can be solved by an appropriate combination of the CTL and the LTL model-checking algorithm
- ▶ The CTL\*-model checking problem is PSPACE-complete



# Symbolic Model Checking

# Boolean functions

- ▶ **Boolean functions**  $f : \mathbb{B}^n \rightarrow \mathbb{B}$  for  $n \geq 0$  where  $\mathbb{B} = \{0, 1\}$ 
  - ▶ examples:  $f(x_1, x_2) = x_1 \wedge (x_2 \vee \neg x_1)$ , and  $f(x_1, x_2) = x_1 \leftrightarrow x_2$
- ▶ **Finite sets are boolean functions**
  - ▶ let  $|S| = N$  and  $2^{n-1} < N \leq 2^n$
  - ▶ encode any element  $s \in S$  as boolean vector of length  $n$ :  
 $[[ \ ]] : S \rightarrow \mathbb{B}^n$
  - ▶  $T \subseteq S$  is represented by  $f_T$  such that:

$$f_T([[s]]) = 1 \quad \text{iff} \quad s \in T$$

- ▶ this is the **characteristic function** of  $T$
- ▶ **Relations are boolean functions**
  - ▶  $\mathcal{R} \subseteq S \times S$  is represented by  $f_{\mathcal{R}}$  such that:

$$f_{\mathcal{R}}([[s]], [[t]]) = 1 \quad \text{iff} \quad (s, t) \in \mathcal{R}$$

# Representing boolean functions

- ▶ **Truth tables**
  - ▶ very space inefficient ( $2^n$  lines)
  - ▶ satisfiability and equivalence check: easy; boolean operations also easy
  - ▶ ... but have to consider exponentially many lines (so are hard)
- ▶ **Propositional formulas**
  - ▶ more compact representation
  - ▶ satisfiability problem is NP-complete (Cook's theorem)
  - ▶ boolean operations are just syntactic operations
- ▶ ... **in Disjunctive Normal Form (DNF)**
  - ▶ satisfiability is easy: find a disjunct that does have complementary literals
  - ▶ negation expensive (dnf of  $\neg\Phi$  may be exponentially longer than  $\Phi$ )
  - ▶ conjunction complicated ( $\Phi \wedge (\Psi_1 \vee \Psi_2) \equiv (\Phi \wedge \Psi_1) \vee (\Phi \wedge \Psi_2)$ )
- ▶ ... **in Conjunctive Normal Form (CNF)**

# Representing boolean functions

<u>representation</u>	<u>compact?</u>	<u>sat</u>	$\wedge$	$\vee$	$\neg$
propositional formula	often	hard	easy	easy	easy
DNF	sometimes	easy	hard	easy	hard
CNF	sometimes	hard	easy	hard	hard
(ordered) truth table	never	hard	hard	hard	hard

# Representing boolean functions

<u>representation</u>	<u>compact?</u>	<u>sat</u>	$\wedge$	$\vee$	$\neg$
propositional formula	often	hard	easy	easy	easy
DNF	sometimes	easy	hard	easy	hard
CNF	sometimes	hard	easy	hard	hard
(ordered) truth table	never	hard	hard	hard	hard
reduced ordered binary decision diagram	often	easy	medium	medium	easy