

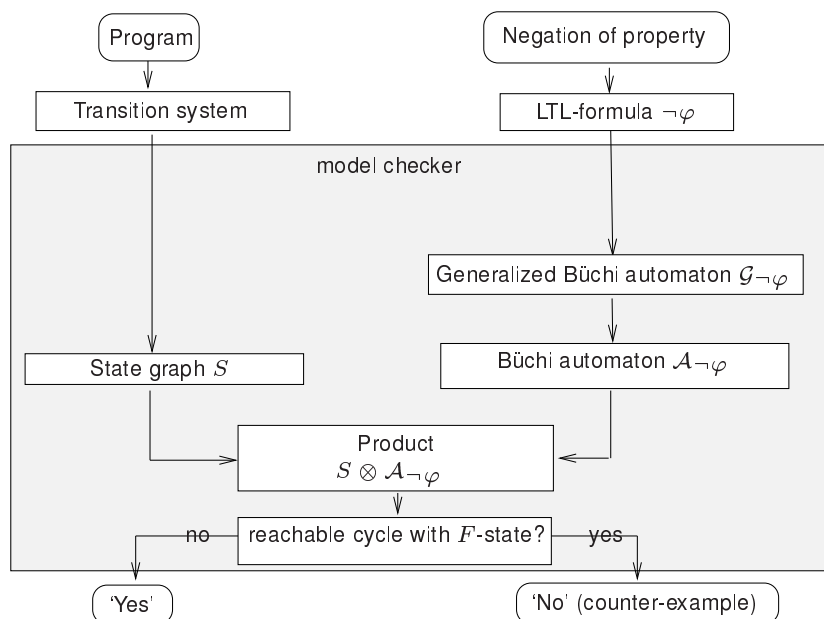
# Verification – Lecture 12

## Model Checking (Complexity)

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### LTL model checking



## The LTL model checking problem

- Input:
  - LTL formula  $\varphi$  over atomic propositions  $AP$
  - Finite state graph (Kripke structure)  $S = (Q, Q_0, E, L)$  with
    - \* finite set of states  $Q$ ,
    - \* initial states  $Q_0 \subseteq Q$ ,
    - \* edges  $E \subseteq Q \times Q$ ,
    - \* labeling function  $L : Q \rightarrow 2^{AP}$ .
- Output:
  - path  $\pi$  in  $T$  such that  $\pi \models \neg\varphi$ , or
  - “yes” if no such path exists.

## From LTL to GNBA

GNBA  $\mathcal{G}_\varphi$  over  $2^{AP}$  for LTL-formula  $\varphi$  with  $\mathcal{L}_\omega(\mathcal{G}_\varphi) = \text{Words}(\varphi)$ :

- Assume  $\varphi$  only contains the operators  $\wedge, \neg, \bigcirc$  and  $\mathcal{U}$ 
  - $\vee, \rightarrow, \diamond, \square, \mathcal{W}$ , and so on, are expressed in terms of these basic operators
- States are *elementary sets* of sub-formulas in  $\varphi$ 
  - for  $\sigma = A_0A_1A_2\dots \in \text{Words}(\varphi)$ , expand  $A_i \subseteq AP$  with sub-formulas of  $\varphi$
  - ... to obtain the infinite word  $\bar{\sigma} = B_0B_1B_2\dots$  such that

$$\psi \in B_i \quad \text{if and only if} \quad \sigma^i = A_iA_{i+1}A_{i+2}\dots \models \psi$$

- $\bar{\sigma}$  is intended to be a run in GNBA  $\mathcal{G}_\varphi$  for  $\sigma$
- Transitions are derived from semantics  $\bigcirc$  and expansion law for  $\mathcal{U}$
- Accept sets guarantee that:  $\bar{\sigma}$  is an accepting run for  $\sigma$  iff  $\sigma \models \varphi$

## Complexity for LTL to NBA

For any LTL-formula  $\varphi$  (over  $AP$ ) there exists an NBA  $\mathcal{A}_\varphi$   
 with  $Words(\varphi) = \mathcal{L}_\omega(\mathcal{A}_\varphi)$  and  
 which can be constructed in time and space in  $2^{\mathcal{O}(|\varphi|)}$ .

## Complexity

- States GNBA  $\mathcal{G}_\varphi$  are elementary sets of formulae in  $closure(\varphi)$ 
  - sets  $B$  can be represented by bit vectors with single bit per subformula  $\psi$  of  $\varphi$
- The number of states in  $\mathcal{G}_\varphi$  is bounded by  $2^{|\text{subf}(\varphi)|}$ 
  - where  $\text{subf}(\varphi)$  denotes the set of all subformulae of  $\varphi$
- The number of accepting sets of  $\mathcal{G}_\varphi$  is bounded above by  $\mathcal{O}(|\varphi|)$
- The number of states in NBA  $\mathcal{A}_\varphi$  is thus bounded by  $2^{\mathcal{O}(|\varphi|)} \cdot \mathcal{O}(|\varphi|)$
- $2^{\mathcal{O}(|\varphi|)} \cdot \mathcal{O}(|\varphi|) = 2^{\mathcal{O}(|\varphi|)}$  ■

## Lower bound

There exists a family of LTL formulas  $\varphi_n$  with  $|\varphi_n| = \mathcal{O}(\text{poly}(n))$   
 such that every NBA  $\mathcal{A}_{\varphi_n}$  for  $\varphi_n$  has at least  $2^n$  states

## Product automaton

- Given:
  - state graph  $S = (Q, Q_0, E, L)$ ,
  - Büchi automaton  $\mathcal{A}_{\neg\varphi} = (Q', Q'_0, \delta', F')$
- Compute: Büchi automaton  $S \otimes \mathcal{A}_{\neg\varphi} = (Q'', Q''_0, \delta'', F'')$ 
  - $Q'' = Q \times Q'$ ,
  - $Q''_0 = Q_0 \times Q'_0$ ,
  - $(q, q') \in \delta''((p, p'), A)$   
 iff  $A = L(p), q' \in \delta'(p', A)$ , and  $(p, q) \in E$ .
  - $F'' = Q \times F'$

## Nested depth-first search

- Idea: perform the two depth-first searches in an *interleaved* way
  - the outer DFS serves to encounter all reachable  $F$ -states
  - the inner DFS seeks for backward edges
- *Nested DFS*
  - on full expansion of  $F$ -state  $s$  in the outer DFS, start inner DFS
  - in inner DFS, visit all states reachable from  $s$  *not visited* in the inner DFS yet
  - no backward edge found? continue the outer DFS (look for next  $F$  state)
- *Counterexample generation*: DFS stack concatenation
  - stack  $U$  for the outer DFS = path fragment from  $s_0 \in I$  to  $s$  (in reversed order)
  - stack  $V$  for the inner DFS = a cycle from state  $s$  to  $s$  (in reversed order)

## Time complexity

The worst-case time complexity of nested DFS is in

$$\mathcal{O}(N+M)$$

where  $N$  is # reachable states in  $S$ , and  $M$  is # edges in state graph

# Complexity for LTL model checking

The time and space complexity of LTL model checking is in  $\mathcal{O}((M + N) \cdot 2^{|\varphi|})$

## On-the-fly LTL model checking

- Idea: find a counter-example *during* the generation of  $Reach(S)$  and  $\mathcal{A}_{\neg\varphi}$ 
    - exploit the fact that  $Reach(S)$  and  $\mathcal{A}_{\neg\varphi}$  can be generated in parallel
- ⇒ Generate  $Reach(S \otimes \mathcal{A}_{\neg\varphi})$  “on demand”
- consider a new vertex only if no accepting cycle has been found yet
  - only consider the successors of a state in  $\mathcal{A}_{\neg\varphi}$  that match current state in  $S$
- ⇒ Possible to find an accepting cycle *without generating  $\mathcal{A}_{\neg\varphi}$  entirely*

# The LTL model-checking problem is PSPACE-complete

The LTL model checking problem is PSPACE-complete.