

Automata, Games, and Verification: Lecture 14

Corollary 1 S_2S is decidable.

S_nS is the monadic second order theory of n successors.

Corollary 2 S_nS is decidable.

Proof:

Repeat exercise for automata on n -ary trees. ■

$S_\omega S$ is the monadic second order theory of ω successors.

Theorem 1 $S_\omega S$ is decidable.

Proof:

We give an effective translation from $S_\omega S$ to S_2S .

- Bijection β from ω^* to $0\mathbb{B}^*$:
 - $\beta(\varepsilon) := \varepsilon$
 - $\beta(vn) := \beta(v)01^n$
 - One-to-many relation R between $S_\omega S$ and S_2S structures: label a position $\beta(x)$ in the binary tree with σ iff x is labeled with σ in the ω -ary tree.
 - Bring given $S_\omega S$ formula in normal form and translate as follows:
 - $x = \varepsilon \mapsto x = \varepsilon$
 - $x = yn \mapsto x = y01^n$ for $n \in \omega$
 - $x \in Y \mapsto x \in Y$
 - $x = y \mapsto x \in Y$
 - $\exists X \dots \mapsto \exists X . (\forall y \in X . \neg 1 \leq y) \wedge \dots$
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19 Alternating Tree Automata

Definition 1 An alternating tree automaton over binary Σ -trees is a tuple $\mathcal{A} = (S, s_0, \delta, \varphi)$:

- S : finite set of states
- $s_0 \in S$
- $\delta : S \times \Sigma \rightarrow \mathbb{B}^+(\{0, 1\} \times S)$ is the transition function.
- φ : acceptance condition (Büchi, parity, ...)

More general: set of directions $\mathcal{D} = \{0, \dots, k-1\}$, $T \subseteq \mathcal{D}^*$, degree $d : \mathcal{D}^* \rightarrow \{1, \dots, k\}$

Definition 2 An alternating tree automaton over Σ -trees is a tuple $\mathcal{A} = (S, s_0, \delta, \varphi)$:

- S : finite set of states
- $s_0 \in S$
- $\delta : S \times \Sigma \times \{1, \dots, k\} \rightarrow \mathbb{B}^+(\{0, 1, \dots, k-1\} \times S)$ is the transition function.
- φ : acceptance condition (Büchi, parity, ...)

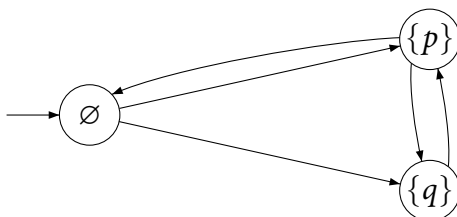
Definition 3 A run of a tree automaton \mathcal{A} on a Σ -tree v is a $\mathcal{D}^* \times S$ -tree (T, r) , s.t.

1. $r(\varepsilon) = (\varepsilon, s_0)$
2. Let $y \in T$ with $r(y) = (x, q)$ and $\delta(q, v(x), d(x)) = \theta$. Then there is a (possibly empty) set $Q = \{(c_0, q'_0), (c_1, q'_1), \dots, (c_n, q'_n)\} \subseteq \{0, \dots, d(x)-1\} \times S$, such that the following hold:
 - $Q \models \theta$
 - for all $0 \leq i \leq n$, we have $y \cdot i \in T$ and $r(y \cdot i) = (x \cdot c_i, q'_i)$.

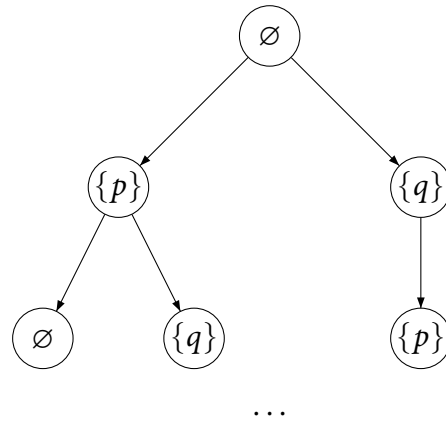
Definition 4 A run is accepting if every branch is accepting (by φ). A Σ -tree is accepted if there exists an accepting run.

Tree automata on Transition Systems

Example: For a transition system:



we build a computation tree t



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Let k be the max number of successors in the transition system $(AP, S, s_0, \rightarrow, L)$. Define a mapping: $f : \{0, \dots, k-1\}^* \rightarrow S$:

- $f(\varepsilon) = s_0$
- Assume there is, for each $s \in S$, a fixed order on the successors s'_1, s'_2, \dots of s
 $f(w \cdot i) = s'_i$ where s'_i is the i th successor of $s = f(w)$.

Definition 5 The computation tree of a transition system $(AP, S, s_0, \rightarrow, L)$ is a 2^{AP} -tree (T, t) with $t(v) = L(f(v))$ and $d(v) = d(f(v))$ for all $v \in T$.

Theorem 2 The computation tree of a transition system is accepted by an alternating tree automaton $\mathcal{A} = (S_{\mathcal{A}}, s_0, \delta, \varphi)$ iff Player 0 has a winning strategy from (s_0, q_0) in the following game:

- $V_0 = S_{\mathcal{A}} \times S_{\mathcal{M}}$
- $V_1 = S_{\mathcal{A}} \times 2^{\{0, \dots, k-1\} \times S_{\mathcal{A}}} \times S_{\mathcal{M}}$
- $E = \{((s, q), (s, \eta, q)) \mid \eta \models \delta(s, L(q), d(q))\}$
 $\cup \{((s, \eta, q), (s', q')) \mid (i, q') \in \eta, s' \text{ is the } i\text{th successor of } s\}$
- winning condition: φ applied to the first component

CTL

Translation from CTL formula φ to alternating Büchi tree automaton \mathcal{A}_{φ} :

- $S = \text{closure}(\varphi) :=$ set of all subformulas and their negations
- for $p \in AP$:
 - $\delta(p, \sigma, k) = \text{true}$ if $p \in \sigma$

- $\delta(p, \sigma, k) = \text{false}$ if $p \notin \sigma$
- $\delta(\neg p, \sigma, k) = \text{false}$ if $p \in \sigma$
- $\delta(\neg p, \sigma, k) = \text{true}$ if $p \notin \sigma$
- $\delta(\varphi \wedge \psi, \sigma, k) = \delta(\varphi, \sigma, k) \wedge \delta(\psi, \sigma, k)$
- $\delta(\varphi \vee \psi, \sigma, k) = \delta(\varphi, \sigma, k) \vee \delta(\psi, \sigma, k)$
- $\delta(\text{AX}\varphi, \sigma, k) = \bigwedge_{c=0}^{k-1} (\sigma, \varphi)$
- $\delta(\text{EX}\varphi, \sigma, k) = \bigvee_{c=0}^{k-1} (\sigma, \varphi)$
- $\delta(\text{A}\varphi \mathcal{U} \psi, \sigma, k) = \delta(\psi, \sigma, k) \vee (\delta(\varphi, \sigma, k) \wedge \bigwedge_{c=0}^{k-1} (\sigma, \text{A}\varphi \mathcal{U} \psi))$
- $\delta(\text{E}\varphi \mathcal{U} \psi, \sigma, k) = \delta(\psi, \sigma, k) \vee (\delta(\varphi, \sigma, k) \wedge \bigvee_{c=0}^{k-1} (\sigma, \text{E}\varphi \mathcal{U} \psi))$
- $\delta(\neg\varphi, \sigma, k) = \overline{\delta(\varphi, \sigma, k)}$

Theorem 3 For every CTL formula φ and a set of directions \mathcal{D} there is an alternating Büchi tree automaton \mathcal{A}_φ such that $\mathcal{L}(\mathcal{A}_{\mathcal{D}, \varphi})$ is exactly the set of \mathcal{D} -branching trees that satisfy φ .