Automata, Games & Verification Summary #12

Today at 2:15pm in SR 016

Seminar "Games, Synthesis, and Robotics" Design and Synthesis of Synchronization Skeletons using Branching Time Temporal Logic

Complementation of Parity Tree Automata

Theorem 1. For each parity tree automaton \mathcal{A} over Σ there is a parity tree automaton \mathcal{A}' with $\mathcal{L}(\mathcal{A}') = T_{\Sigma} - \mathcal{L}(\mathcal{A})$.

$$\mathcal{A} \text{ does not accept } t \text{ iff}$$
(1) there is a $(M \to \{0, 1\})$ -tree v such that
(2) for all $i_0, i_1, i_2, \ldots \in \{0, 1\}^{\omega}$
(3) for all $\tau_0, \tau_1, \ldots \in M^{\omega}$
(4) if
• for all $j,$
 $\tau_j = (q, a, q'_0, q'_1)$
 $\Rightarrow a = t(i_0, i_1, \ldots, i_j) \text{ and}$
• $i_0 i_1 \ldots = v(\varepsilon)(\tau_0) v(i_0)(\tau_1) \ldots$
then the generated state sequence $q_0 q_1 \ldots$
with $q_0 = s_0, (q_j, a, q^0, q^1) = \tau_j,$
 $q_{j+1} = q^{v(i_0, \ldots, i_{j-1})(\tau_j)}$
violates $c.$

Monadic Second-Order Theory of Two Successors (S2S) Syntax:

- first-order variable set $V_1 = \{x_0, x_1, \ldots\}$
- second-order variable set $V_2 = \{X_0, X_1, \ldots\}$
- Terms: $t ::= \epsilon \mid x \mid t0 \mid t1$
- Formulas $\varphi ::= t \in X \mid t_1 = t_2 \mid \neg \varphi \mid \varphi_0 \lor \varphi_1 \mid \exists x. \varphi \mid \exists X. \varphi$

Semantics:

- first-order valuation $\sigma_1: V_1 \to \mathbb{B}^*$
- second-order valuation $\sigma_2: V_2 \to 2^{\mathbb{B}^*}$
- terms: $\llbracket \epsilon \rrbracket = \epsilon$, $\llbracket t 0 \rrbracket_{\sigma_1} = \llbracket t \rrbracket_{\sigma_1} 0$, etc.
- formulas: $\sigma_1, \sigma_2 \models \exists x_i. \varphi$ iff there is a $a \in \mathbb{B}^*$ s.t.

$$\sigma_1'(y) = \begin{cases} \sigma_1(y) & \text{if } x \neq y, \\ a & \text{otherwise;} \end{cases} \quad \text{and } \sigma_1', \sigma_2 \models \varphi$$

etc. Bernd Finkbeiner **Theorem 2.** For each Muller tree automaton $\mathcal{A} = (S, s_0, M, \mathcal{F})$ over $\Sigma = 2^{V_2}$ there is a S2S formula φ over V_2 s.t. $t \in \mathcal{L}(\mathcal{A})$ iff $\sigma_2 \models \varphi$ where $\sigma_2(P) = \{q \in \{0,1\}^* \mid P \in t(q)\}.$

Theorem 3. For every S2S formula φ over V_1, V_2 there is a Muller tree automaton \mathcal{A} over $\Sigma = 2^{V_1 \cup V_2}$ such that $t \in \mathcal{L}(\mathcal{A})$ iff $\sigma_1, \sigma_2 \models \varphi$ where

$$\sigma_1(x) = q \text{ iff } x \in t(q);$$

$$\sigma_2(X) = \{q \in \{0,1\}^* \mid X \in t(q)\}.$$

Corollary 1.

S2S is decidable.

- SnS is the monadic second order theory of n successors.
 Corollary 2.
 SnS is decidable.
- $S\omega S$ is the monadic second order theory of ω successors.

Theorem 4. $S\omega S$ is decidable.

• WS2S is the weak monadic second order theory of two successors.

 $\sigma_1, \sigma_2 \models \exists X. \varphi \text{ iff there is a finite } A \subseteq \mathbb{B}^* \text{ s.t.}$

$$\sigma'_2(Y) = \begin{cases} \sigma_2(Y) & \text{if } X \neq Y \\ A & \text{otherwise} \end{cases} \quad \text{and} \quad \sigma_1, \sigma'_2 \models \varphi.$$

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Corollary 3.

WS2S is decidable.

Theorem 5. For a language $L \subseteq T_{\Sigma}$, the following are equivalent: 1. Both L and its complement are recognizable by a Büchi tree automaton.

2. L is WS2S-definable.

Corollary 4. WS2S is strictly weaker than S2S.