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# Limit Your Consumption!

## Finding Bounds in Average-energy Games

Joint work with Kim G. Larsen and Simon Laursen (Aalborg University)

Martin Zimmermann

Saarland University

April, 3rd 2016

QAPL 16

# Motivation

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  - non-terminating
  - interacting with a possibly antagonistic environment
  - communication-intensive

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  - two players
  - infinite duration
  - perfect information
  - system player wins if specification is satisfied

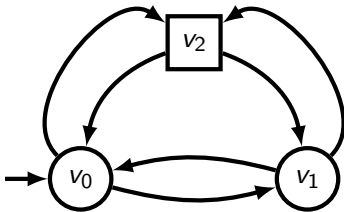
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- Here: graph-based games with quantitative winning conditions modeling consumption of a resource

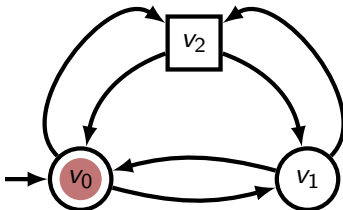
# An Example

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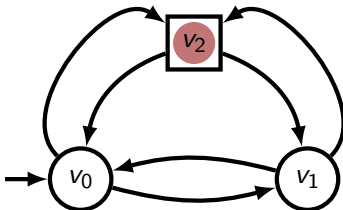


A play:

$v_0$

# An Example

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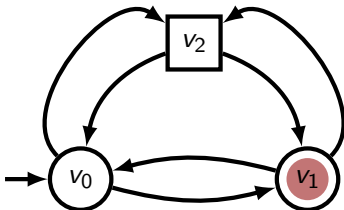


A play:

$v_0 \ v_2$

# An Example

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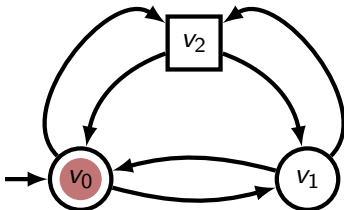
A play:

$v_0$   $v_2$   $v_1$



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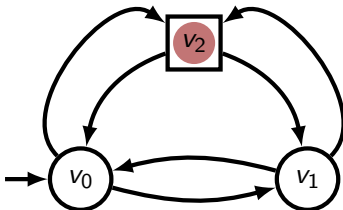


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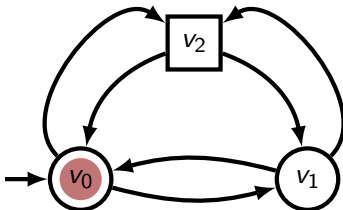


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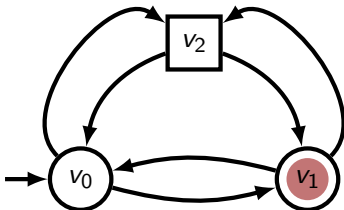


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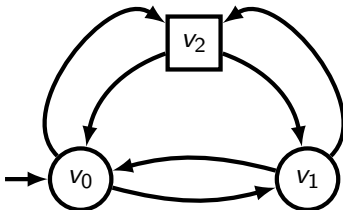


A play:

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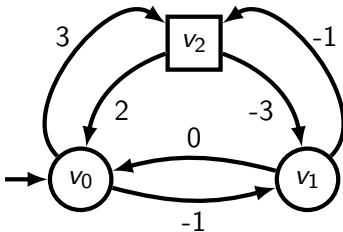


A play:

$v_0$   $v_2$   $v_1$   $v_0$   $v_2$   $v_0$   $v_1$   $\dots$

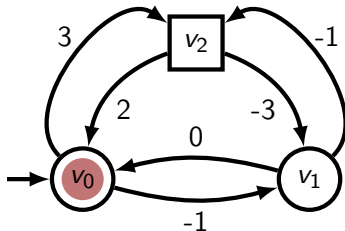
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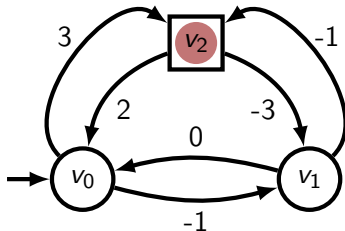


A play (with energy levels):

$(v_0, 0)$

# An Example

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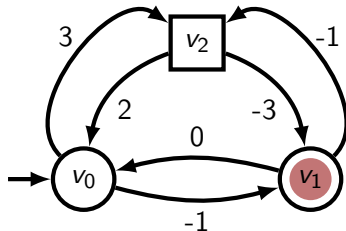
A play (with energy levels):

$(v_0, 0)$   $(v_2, 3)$



# An Example

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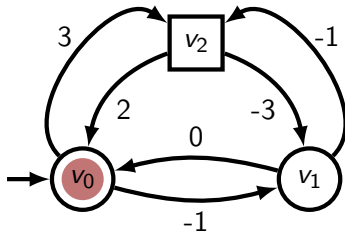


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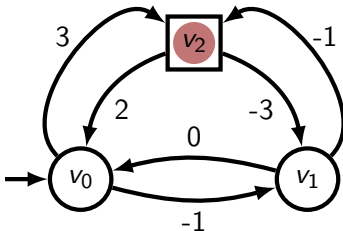


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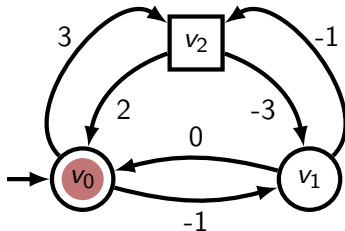


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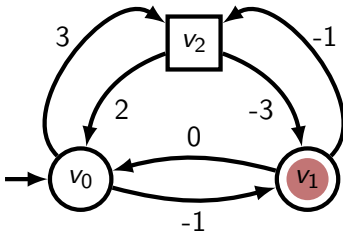


A play (with energy levels):

$(v_0, 0)$   $(v_2, 3)$   $(v_1, 0)$   $(v_0, 0)$   $(v_2, 3)$   $(v_0, 5)$

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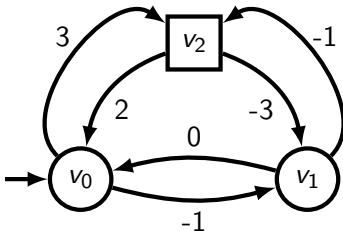


A play (with energy levels):

$(v_0, 0)$   $(v_2, 3)$   $(v_1, 0)$   $(v_0, 0)$   $(v_2, 3)$   $(v_0, 5)$   $(v_1, 4)$

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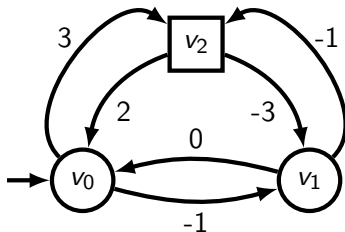


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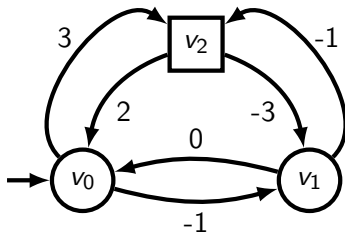


A strategy:

$\rightarrow (v_0, 0)$

# An Example

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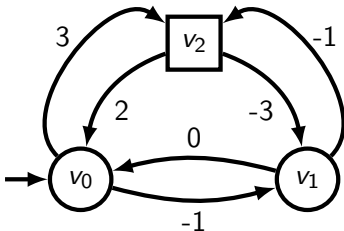
A strategy:

$$\rightarrow (v_0, 0) \rightarrow (v_2, 3)$$

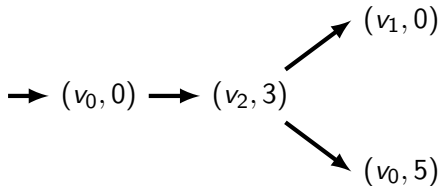


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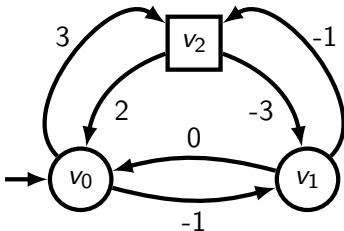


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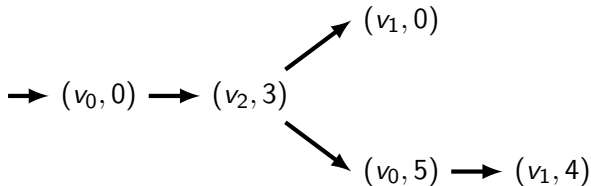


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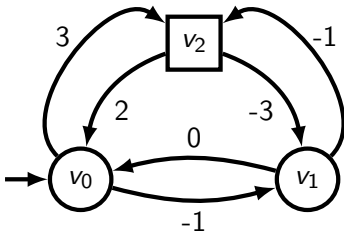


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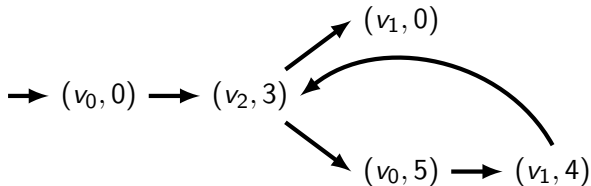


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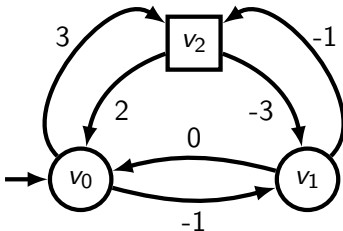


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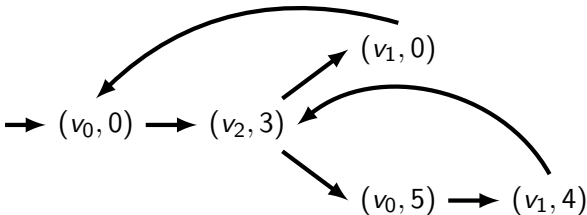


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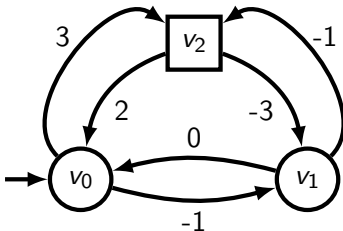
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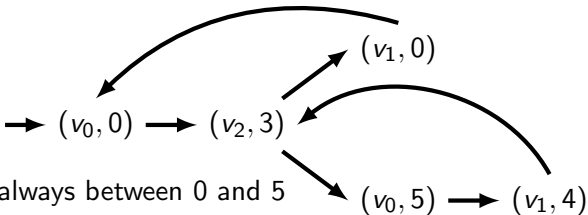
A strategy:



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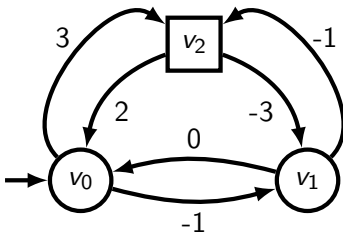


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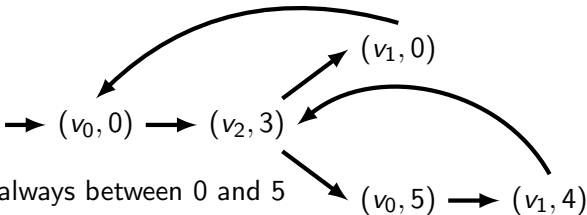


- Energy level always between 0 and 5

# An Example



A strategy:



- Energy level always between 0 and 5
- Average energy level at most 4

# Previous Work

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objective	Complexity	Memory Requirements
$EG_L$	$NP \cap co-NP$	memoryless
$EG_{LU}$	EXPTIME-complete	pseudopolynomial

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- W.l.o.g.: fix lower bound 0
- In all problems, lower and upper bounds part of the input.
- Here: upper bound existentially quantified.

# Objectives

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Capacity  $cap \in \mathbb{N}$ , threshold  $t \in \mathbb{N}$

- $EG_L = \{v_0 v_1 \dots \mid \forall n. 0 \leq EL(v_0 \dots v_n)\}$
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- $AE_L(t) = EG_L \cap AE(t)$
- $AE_{LU}(cap, t) = EG_{LU}(cap) \cap AE(t)$

# Finding Bounds in Average-energy Games

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**Input:** Weighted arena  $\mathcal{A}$

**Question:** Exists a threshold  $t \in \mathbb{N}$  s.t. Player 0 wins  $(\mathcal{A}, \text{AE}_L(t))$ ?

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.. which is in  $2\text{EXPTIME}$  [Juhl, Larsen, Raskin '13].



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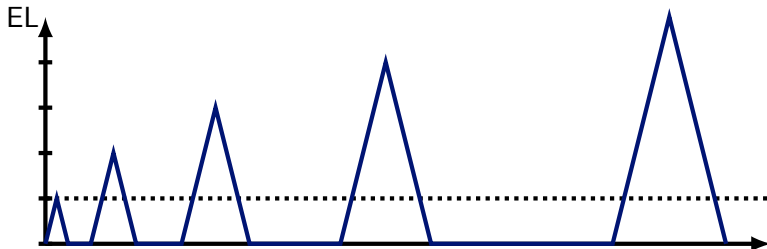
**Note:**

The direction  $\exists cap \Rightarrow \exists t$  is trivial.

$$\exists t \Rightarrow \exists cap$$

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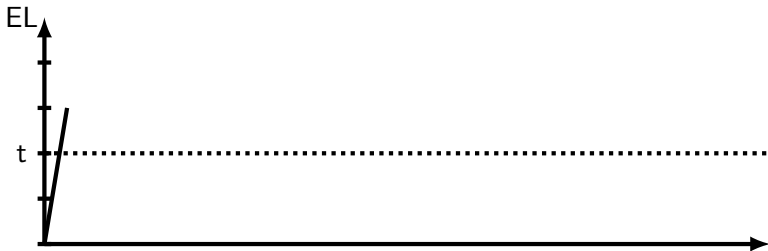
- Obstacle: average can be bounded while energy level is unbounded



$$\exists t \Rightarrow \exists cap$$

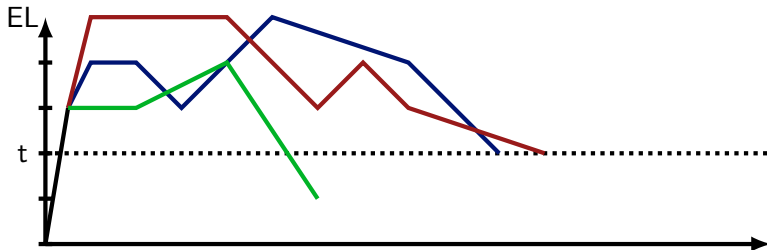
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- But: every time energy level increases above threshold  $t$  on average, it drops below  $t$  later
- Crossings are characterized by vertex  $v$  and energy level in range  $t + 1, \dots, t + W$
- For every such combination play like in situation with smallest maximal energy level before next drop below  $t$



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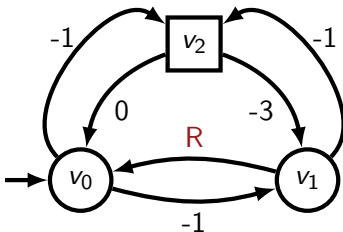


- This strategy bounds the energy level by some *cap*.

# Recharge Games

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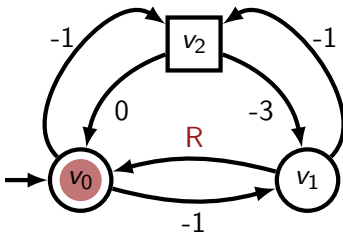
- Previously: positive and negative weights
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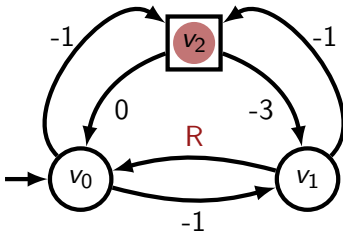
A play with  $cap = 5$ :

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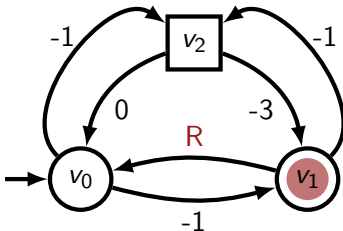


A play with  $cap = 5$ :

$(v_0, 5)$   $(v_2, 4)$

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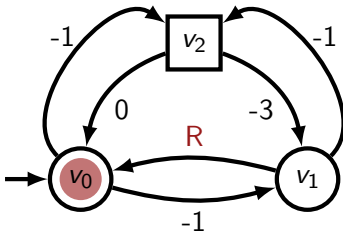
A play with  $cap = 5$ :

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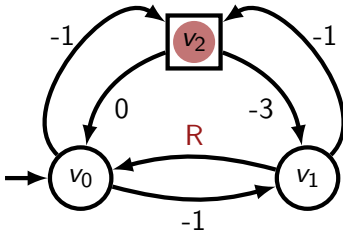


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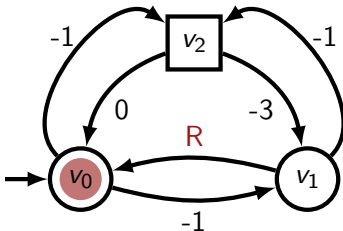


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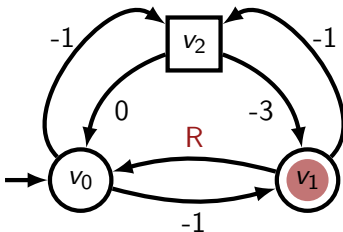


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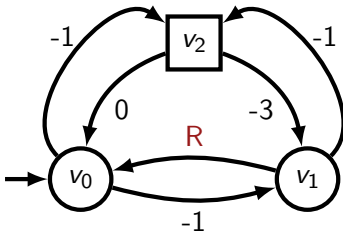


A play with  $cap = 5$ :

$(v_0, 5)$   $(v_2, 4)$   $(v_1, 1)$   $(v_0, 5)$   $(v_2, 4)$   $(v_0, 4)$   $(v_1, 3)$

# Recharge Games

- Previously: positive and negative weights
- Now: only negative weights and recharge edges that recharge to a fixed capacity  $cap$ .



A play with  $cap = 5$ :

$(v_0, 5)$   $(v_2, 4)$   $(v_1, 1)$   $(v_0, 5)$   $(v_2, 4)$   $(v_0, 4)$   $(v_1, 3)$   $\dots$

# Objectives

---

- $RE(cap) = \{v_0 v_1 \cdots \mid \forall n. EL_{cap}(v_0 \cdots v_n) \geq 0\}$
- $AR(cap, t) = RE(cap) \cap$   
 $\{v_0 v_1 \cdots \mid \limsup_{n \rightarrow \infty} \frac{1}{n} \sum_{i=0}^{n-1} EL_{cap}(v_0 \cdots v_i) \leq t\}$

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## Theorem

*The problem*

**Input:** *Weighted arena  $\mathcal{A}$ ,  $\text{cap} \in \mathbb{N}$ , and  $t \in \mathbb{N}$ .*

**Question:** *Does Player 0 win  $(\mathcal{A}, \text{AR}(\text{cap}, t))$ ?*

*is EXPTIME-complete.*

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## Proof:

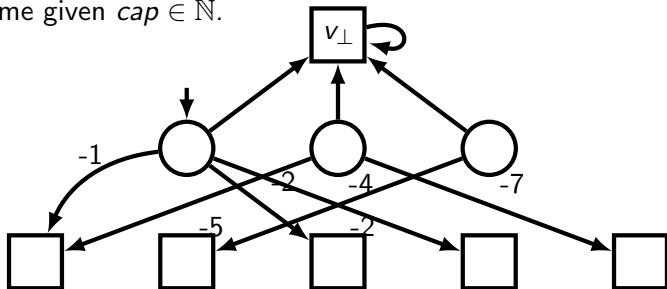
Upper bound: Reduction to mean-payoff games.

Lower bound: Reduction from countdown games.



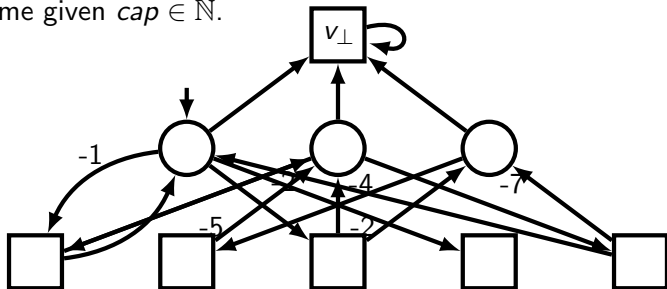
# Proof Sketch

A countdown game. Objective: reach  $v_{\perp}$  with energy-level  $-cap$  for some given  $cap \in \mathbb{N}$ .



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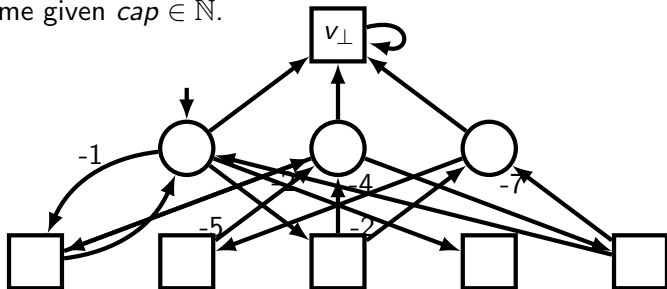


**Theorem (Jurdziński, Sproston, Laroussini '08)**

*Solving countdown games is EXPTIME-complete.*

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## Theorem (Jurdziński, Sproston, Laroussini '08)

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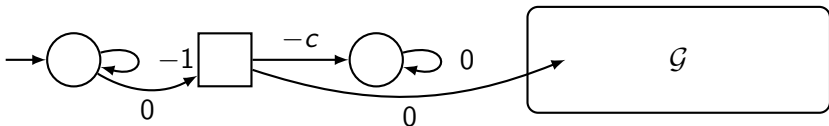
Turn countdown game into average bounded recharge game:  
capacity  $cap$  and threshold 0.

# Who is to Blame?

---

## Theorem

*Solving average-bounded recharge games with existentially quantified capacity and a given threshold is  $\text{EXPTIME}$ -hard.*

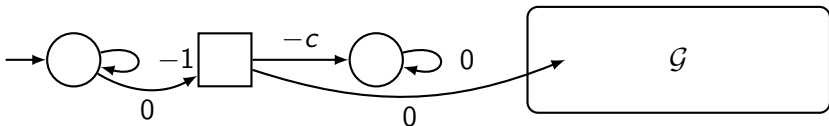


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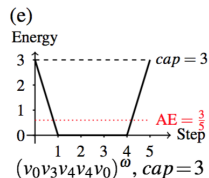
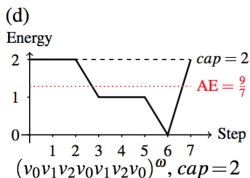
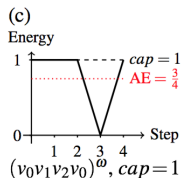
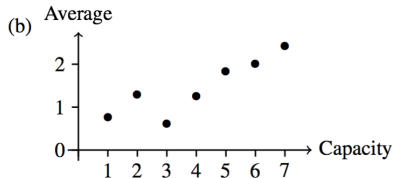
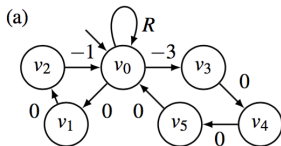
## Theorem

*The problem*

**Input:** *Weighted arena  $\mathcal{A}$*

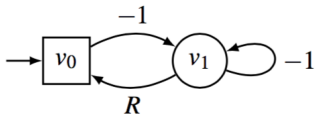
**Question:** *Exists a capacity  $cap$  s.t. Player 0 wins  $(\mathcal{A}, \text{RE}(cap))$ ?  
is in  $\text{PTIME}$ .*

# Tradeoffs: Capacity vs. Average

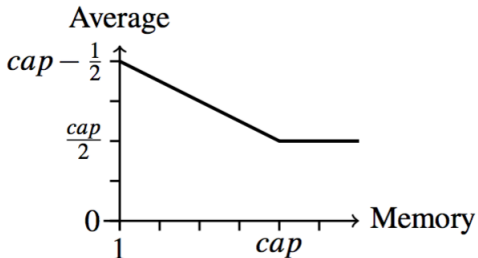


- Available loops depend on capacity
- Tradeoff not monotonic
- Cause of tradeoff: recharge to  $cap$  at recharge-edges

# Tradeoffs: Average vs. Memory



- With  $n$  memory states, use self-loop  $n - 1$  times
- Then, recharge to level  $cap$



# Future Work

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Many problems remain open:

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- Multi-dimensional games