

Verification

Lecture 3

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Plan for today

- ▶ CTL model checking
 - ▶ The basic algorithm
 - ▶ Fairness
 - ▶ Counterexamples and witnesses

Review: Computation tree logic

modal logic over infinite **trees** [Clarke & Emerson 1981]

▶ Statements over states

- ▶ $a \in AP$ atomic proposition
- ▶ $\neg \Phi$ and $\Phi \wedge \Psi$ negation and conjunction
- ▶ $E \varphi$ there exists a path fulfilling φ
- ▶ $A \varphi$ all paths fulfill φ

▶ Statements over paths

- ▶ $X \Phi$ the next state fulfills Φ
- ▶ $\Phi U \Psi$ Φ holds until a Ψ -state is reached

⇒ note that X and U alternate with A and E

- ▶ $AXX\Phi$ and $AEX\Phi \notin \text{CTL}$, but $AXAX\Phi$ and $AXEX\Phi \in \text{CTL}$

Alternative syntax: $E \approx \exists, A \approx \forall, X \approx \bigcirc, G \approx \square, F \approx \diamond$.

Review: Existential normal form (ENF)

The set of CTL formulas in existential normal form (ENF) is given by:

$$\Phi ::= \text{true} \mid a \mid \Phi_1 \wedge \Phi_2 \mid \neg\Phi \mid EX\Phi \mid E(\Phi_1 U \Phi_2) \mid EG\Phi$$

For each CTL formula, there exists an equivalent CTL formula in ENF

$$AX\Phi \quad \equiv \quad \neg EX\neg\Phi$$

$$A(\Phi U \Psi) \quad \equiv \quad \neg E(\neg\Psi U (\neg\Phi \wedge \neg\Psi)) \wedge \neg EG\neg\Psi$$

Review: Model checking CTL

- ▶ How to check whether state graph TS satisfies CTL formula $\widehat{\Phi}$?
 - ▶ convert the formula $\widehat{\Phi}$ into the equivalent Φ in ENF
 - ▶ compute recursively the set $Sat(\Phi) = \{q \in S \mid q \models \Phi\}$
 - ▶ $TS \models \Phi$ if and only if each initial state of TS belongs to $Sat(\Phi)$
- ▶ Recursive **bottom-up** computation of $Sat(\Phi)$:
 - ▶ consider the parse-tree of Φ
 - ▶ start to compute $Sat(a_i)$, for all leaves in the tree
 - ▶ then go one level up in the tree and determine $Sat(\cdot)$ for these nodes

$$\text{e.g.,: } Sat(\underbrace{\Psi_1 \wedge \Psi_2}_{\text{node at level } i}) = Sat(\underbrace{\Psi_1}_{\text{node at level } i-1}) \cap Sat(\underbrace{\Psi_2}_{\text{node at level } i-1})$$

- ▶ then go one level up and determine $Sat(\cdot)$ of these nodes
- ▶ and so on..... until the root is treated, i.e., $Sat(\Phi)$ is computed

Basic algorithm

Require: finite transition system TS with states S and initial states I , and CTL formula Φ (both over AP)

Ensure: $TS \models \Phi$

{compute the sets $Sat(\Phi) = \{q \in S \mid q \models \Phi\}$ }

for all $i \leq |\Phi|$ **do**

for all $\Psi \in Sub(\Phi)$ with $|\Psi| = i$ **do**

 compute $Sat(\Psi)$ from $Sat(\Psi')$ {for maximal proper $\Psi' \in Sub(\Psi)$ }

end for

end for

return $I \subseteq Sat(\Phi)$

Characterization of *Sat* (1)

For all CTL formulas Φ, Ψ over AP it holds:

$$\text{Sat}(\text{true}) = S$$

$$\text{Sat}(a) = \{q \in S \mid a \in L(q)\}, \text{ for any } a \in AP$$

$$\text{Sat}(\Phi \wedge \Psi) = \text{Sat}(\Phi) \cap \text{Sat}(\Psi)$$

$$\text{Sat}(\neg\Phi) = S \setminus \text{Sat}(\Phi)$$

$$\text{Sat}(\text{EX } \Phi) = \{q \in S \mid \text{Post}(q) \cap \text{Sat}(\Phi) \neq \emptyset\}$$

for a given finite transition system without terminal states

Characterization of *Sat* (2)

- ▶ $Sat(E(\Phi \cup \Psi))$ is the smallest subset T of S , such that:

$$(1) Sat(\Psi) \subseteq T \quad \text{and} \quad (2) (q \in Sat(\Phi) \text{ and } Post(q) \cap T \neq \emptyset) \Rightarrow q \in T$$

- ▶ $Sat(EG \Phi)$ is the largest subset T of S , such that:

$$(3) T \subseteq Sat(\Phi) \quad \text{and} \quad (4) q \in T \text{ implies } Post(q) \cap T \neq \emptyset$$

Computing $Sat(E(\Phi \cup \Psi))$ (1)

- ▶ $Sat(E(\Phi \cup \Psi))$ is the smallest set $T \subseteq S$ such that:

$$(1) Sat(\Psi) \subseteq T \quad \text{and} \quad (2) (q \in Sat(\Phi) \text{ and } Post(q) \cap T \neq \emptyset) \Rightarrow q \in T$$

- ▶ This suggests to compute $Sat(E(\Phi \cup \Psi))$ iteratively:

$$T_0 = Sat(\Psi) \quad \text{and} \quad T_{i+1} = T_i \cup \{q \in Sat(\Phi) \mid Post(q) \cap T_i \neq \emptyset\}$$

- ▶ T_i = states that can reach a Ψ -state in at most i steps via a Φ -path
- ▶ By induction on j it follows:

$$T_0 \subseteq T_1 \subseteq \dots \subseteq T_j \subseteq T_{j+1} \subseteq \dots \subseteq Sat(E(\Phi \cup \Psi))$$

Computing $Sat(E(\Phi \cup \Psi))$ (2)

- ▶ TS is finite, so for some $j \geq 0$ we have: $T_j = T_{j+1} = T_{j+2} = \dots$
- ▶ Therefore: $T_j = T_j \cup \{q \in Sat(\Phi) \mid Post(q) \cap T_j \neq \emptyset\}$
- ▶ Hence: $\{q \in Sat(\Phi) \mid Post(q) \cap T_j \neq \emptyset\} \subseteq T_j$
 - ▶ hence, T_j satisfies (2), i.e.,
 $(q \in Sat(\Phi) \text{ and } Post(q) \cap T_j \neq \emptyset) \Rightarrow q \in T_j$
 - ▶ further, $Sat(\Psi) = T_0 \subseteq T_j$ so, T_j satisfies (1), i.e. $Sat(\Psi) \subseteq T_j$
- ▶ As $Sat(E(\Phi \cup \Psi))$ is the smallest set satisfying (1) and (2):
 - ▶ $Sat(E(\Phi \cup \Psi)) \subseteq T_j$ and thus $Sat(E(\Phi \cup \Psi)) = T_j$
- ▶ Hence: $T_0 \subsetneq T_1 \subsetneq T_2 \subsetneq \dots \subsetneq T_j = T_{j+1} = \dots = Sat(E(\Phi \cup \Psi))$

Computing $Sat(E(\Phi \cup \Psi))$ (3)

Require: finite transition system with states S CTL-formula $E(\Phi \cup \Psi)$

Ensure: $Sat(E(\Phi \cup \Psi)) = \{q \in S \mid q \models E(\Phi \cup \Psi)\}$

$V := Sat(\Psi)$; $\{V$ administers states q with $q \models E(\Phi \cup \Psi)\}$

$T := V$; $\{T$ contains the already visited states q with $q \models E(\Phi \cup \Psi)\}$

while $V \neq \emptyset$ **do**

let $q' \in V$;

$V := V \setminus \{q'\}$;

for all $q \in Pre(q')$ **do**

if $q \in Sat(\Phi) \setminus T$ **then** $V := V \cup \{q\}$; $T := T \cup \{q\}$; **endif**

end for

end while

return T

Computing $Sat(EG \Phi)$

$V := S \setminus Sat(\Phi)$; $\{V$ contains any not visited q' with $q' \neq EG \Phi\}$

$T := Sat(\Phi)$; $\{T$ contains any q for which $q \models EG \Phi$ has not yet been disproven}

for all $q \in Sat(\Phi)$ **do** $c[q] := |Post(q)|$; **od** {initialize array c }

while $V \neq \emptyset$ **do**

 {loop invariant: $c[q] = |Post(q) \cap (T \cup V)|$ }

let $q' \in V$; $\{q' \neq \Phi\}$

$V := V \setminus \{q'\}$; $\{q'$ has been considered}

for all $q \in Pre(q')$ **do**

if $q \in T$ **then**

$c[q] := c[q] - 1$; {update counter $c[q]$ for predecessor q of q' }

if $c[q] = 0$ **then**

$T := T \setminus \{q\}$; $V := V \cup \{q\}$; $\{q$ does not have any successor in $T\}$

end if

end if

end for

end while

return T

Alternative algorithm for $Sat(EG \Phi)$

1. Consider only state q if $q \models \Phi$, otherwise eliminate q
 - change states to $S' = Sat(\Phi)$,
 - \Rightarrow all removed states will not satisfy $EG \Phi$, and thus can be safely removed
2. Determine all non-trivial strongly connected components in $TS[\Phi]$
 - non-trivial SCC = maximal, connected subgraph with at least one edge
 - \Rightarrow any state in such SCC satisfies $EG \Phi$
3. $q \models EG \Phi$ is equivalent to "some SCC is reachable from q "
 - this search can be done in a backward manner

Complexity

For transition system TS with N states and M edges,
and CTL formula Φ , the CTL model-checking problem $TS \models \Phi$
can be solved in time $\mathcal{O}(|\Phi| \cdot (N + M))$

this applies to both algorithms for EG Φ

Fairness

Arbiter discussed yesterday

```
typedef enum A, B, C, X selection;
typedef enum IDLE, READY, BUSY controller_state;
typedef enum NO_REQ, REQ, HAVE_TOKEN client_state;

module main(clk);
    input clk;
    output ackA, ackB, ackC;
    selection wire sel;
    wire active;

    assign active = pass_tokenA || pass_tokenB || pass_tokenC;

    controller controllerA(clk, reqA, ackA, sel, pass_tokenA, A);
    controller controllerB(clk, reqB, ackB, sel, pass_tokenB, B);
    controller controllerC(clk, reqC, ackC, sel, pass_tokenC, C);
    arbiter arbiter(clk, sel, active);
    client clientA(clk, reqA, ackA);
    client clientB(clk, reqB, ackB);
    client clientC(clk, reqC, ackC);
endmodule
```


Model checking (1)

- ▶ **Mutual exclusion:** No two different acks are given at the same time.

```
AG ( !(ackA=1 * ackB=1 + ackB=1 * ackC=1 + ackC=1  
* ackA=1) );
```

```
vis> read_verilog arbiter.v  
vis> init_verify  
vis> model_check arbiter.ct1
```

```
# MC: formula passed -- AG(!((((ackA=1 * ackB=1) +  
(ackB=1 * ackC=1)) + (ackC=1 * ackA=1))))
```

Model checking (2)

- ▶ **Responsiveness:** Every request is eventually followed by an ack

```
AG( (reqA = 1) -> AF(ackA = 1) );
```

```
AG( (reqB = 1) -> AF(ackB = 1) );
```

```
AG( (reqC = 1) -> AF(ackC = 1) );
```

```
vis> read_verilog arbiter.v
vis> init_verify
vis> model_check arbiter.ct1
```

```
# MC: formula passed -- AG(!(((ackA=1 * ackB=1) +
(ackB=1 * ackC=1)) + (ackC=1 * ackA=1))))
```

```
# MC: formula failed -- AG((reqA=1 -> AF(ackA=1)))
```

```
# MC: formula failed -- AG((reqB=1 -> AF(ackB=1)))
```

```
# MC: formula failed -- AG((reqC=1 -> AF(ackC=1)))
```

```
module client(clk, req, ack);  
    input clk, ack;  
    output req;  
  
    reg req;  
    client_state reg state;  
  
    wire rand_choice;  
  
    initial req = 0;  
    initial state = NO_REQ;  
  
    assign rand_choice = $ND(0,1);  
  
    always @(posedge clk) begin  
        case(state)  
            NO_REQ:  
                if (rand_choice)  
                    begin  
                        req = 1;  
                        state = REQ;  
                    end  
        end
```

```
REQ:
    if (ack) state = HAVE_TOKEN;
HAVE_TOKEN:
    if (rand_choice)
        begin
            req = 0;
            state = NO_REQ;
        end
    endcase
end
endmodule
```

Fairness constraints

Fairness: We are only interested in paths where the clients release the token infinitely often.

arbiter.fair:

```
!(clientA.state=HAVE_TOKEN);  
!(clientB.state=HAVE_TOKEN);  
!(clientC.state=HAVE_TOKEN);
```

```
vis> read_fairness arbiter.fair
```

```
vis> model_check arbiter.ctl
```

```
# MC: formula passed -- AG(!(((ackA=1 * ackB=1) +  
(ackB=1 * ackC=1)) + (ackC=1 * ackA=1))))
```

```
# MC: formula passed -- AG((reqA=1 -> AF(ackA=1)))
```

```
# MC: formula passed -- AG((reqB=1 -> AF(ackB=1)))
```

```
# MC: formula passed -- AG((reqC=1 -> AF(ackC=1)))
```